# A METHOD FOR COMPUTING THE DISCRETE SPECTRUM BASIC TO MULTI-GROUP TRANSPORT THEORY 

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#### Abstract

Elementary considerations are used to develop a computational method for establishing the discrete spectrum for a general multi-group model basic to radiation transport.


## INTRODUCTION

We consider here the multi-group transport equation written as

$$
\begin{equation*}
\mu \frac{\partial}{\partial z} \boldsymbol{\Psi}(z, \mu)+\mathbf{S} \boldsymbol{\Psi}(z, \mu)=\sum_{l=0}^{L} P_{l}(\mu) \mathbf{T}_{l} \int_{-1}^{1} P_{l}\left(\mu^{\prime}\right) \boldsymbol{\Psi}\left(z, \mu^{\prime}\right) \mathrm{d} \mu^{\prime} \tag{1}
\end{equation*}
$$

where the Legendre polynomials are denoted by $P_{l}(\mu)$ and the transfer matrices $\mathbf{T}_{l}$ are such that particle transfer (by, say, scattering and/or fission) between and within all energy groups is allowed. In addition, the elements $\psi_{1}(z, \mu), \psi_{2}(z, \mu), \ldots, \psi_{M}(z, \mu)$ of the $M$-vector $\boldsymbol{\Psi}(z, \mu)$ are the group angular fluxes, the elements $s_{1}, s_{2}, \ldots, s_{M}$ of the diagonal $\mathbf{S}$ matrix are the group total cross sections, $z$ is the position variable measured in cm and $\mu$ is the direction cosine, with respect to the positive $z$ axis, that defines the direction of motion.

In order to use dimensionless units we introduce an optical variable $x=z s_{\min }$, where $s_{\min }$ is the minimum of the set $\left\{s_{i}\right\}$, and rewrite equation (1) as

$$
\begin{equation*}
\mu \frac{\partial}{\partial x} \boldsymbol{\Psi}(x, \mu)+\boldsymbol{\Sigma} \boldsymbol{\Psi}(x, \mu)=\sum_{l=0}^{L} P_{l}(\mu) \mathbf{C}_{l} \int_{-1}^{1} P_{l}\left(\mu^{\prime}\right) \boldsymbol{\Psi}\left(x, \mu^{\prime}\right) \mathrm{d} \mu^{\prime} \tag{2}
\end{equation*}
$$

where the diagonal matrix $\Sigma$ has entries $\sigma_{i}=s_{i} / s_{\text {min }}$ and where the dimensionless transfer matrices are defined by $\mathbf{C}_{l}=\mathbf{T}_{l} / s_{\text {min }}$.

## THE DISPERSION FUNCTION

In order to find elementary solutions of equation (2) we start by substituting

$$
\begin{equation*}
\Psi(\xi: x, \mu)=\exp (-x / \xi) \Phi(\xi, \mu) \tag{3}
\end{equation*}
$$

into equation (2) to obtain

$$
\begin{equation*}
(\xi \Sigma-\mu \mathbf{I}) \boldsymbol{\Phi}(\xi, \mu)=\xi \sum_{k=0}^{L} P_{k}(\mu) \mathbf{C}_{k} \mathbf{G}_{k}(\xi) \mathbf{M}(\xi) \tag{4}
\end{equation*}
$$

where we have defined

$$
\begin{equation*}
\mathbf{G}_{k}(\xi) \mathbf{M}(\xi)=\int_{-1}^{1} P_{k}(\mu) \Phi(\xi, \mu) \mathrm{d} \mu . \tag{5}
\end{equation*}
$$

We can now multiply equation (4) by $P_{I}(\mu)$ and integrate over $\mu$ from -1 to 1 to find

$$
\begin{equation*}
\left[\xi \mathbf{h}_{l} \mathbf{G}_{l}(\xi)-(l+1) \mathbf{G}_{l+1}(\xi)-l \mathbf{G}_{l-1}(\xi)\right] \mathbf{M}(\xi)=\mathbf{0} \tag{6}
\end{equation*}
$$

where we have defined

$$
\begin{equation*}
\mathbf{h}_{l}=(2 l+1) \Sigma-2 \mathbf{C}_{l} . \tag{7}
\end{equation*}
$$

We now define

$$
\begin{equation*}
\mathbf{G}_{0}(\xi)=\mathbf{I} \tag{8}
\end{equation*}
$$

so that

$$
\begin{equation*}
\int_{-1}^{1} \boldsymbol{\Phi}(\xi, \mu) \mathrm{d} \mu=\mathbf{M}(\xi) \tag{9}
\end{equation*}
$$

We thus consider the polynomial matrices $\mathbf{G}_{l}(\xi)$ to be defined for all $\xi$ by equation (8) and the recursion formula

$$
\begin{equation*}
\xi \mathbf{h}_{l} \mathbf{G}_{l}(\xi)=(l+1) \mathbf{G}_{l+1}(\xi)+l \mathbf{G}_{i-1}(\xi) \tag{10}
\end{equation*}
$$

for $l \geqslant 0$.
For the discrete spectrum $\xi \notin[-1,1]$, we can solve equation (4) to obtain

$$
\begin{equation*}
\boldsymbol{\Phi}(\xi, \mu)=\xi(\xi \mathbf{\Sigma}-\mu \mathbf{I})^{-1} \mathbf{G}(\xi, \mu) \mathbf{M}(\xi) \tag{11}
\end{equation*}
$$

where

$$
\begin{equation*}
\mathbf{G}(\xi, \mu)=\sum_{l=0}^{L} \mathbf{C}_{l} \mathbf{G}_{l}(\xi) P_{l}(\mu) \tag{12}
\end{equation*}
$$

and we can integrate equation (11) to find

$$
\begin{equation*}
\boldsymbol{\Lambda}(\xi) \mathbf{M}(\xi)=\mathbf{0} \tag{13}
\end{equation*}
$$

where

$$
\begin{equation*}
\boldsymbol{\Lambda}(\xi)=\mathbf{I}+\xi \int_{-1}^{1}(\mu \mathbf{I}-\xi \mathbf{\Sigma})^{-1} \mathbf{G}(\xi, \mu) \mathrm{d} \mu \tag{14}
\end{equation*}
$$

We therefore take our dispersion function to be $\Lambda(\xi)=\operatorname{det} \boldsymbol{A}(\xi)$, so that the discrete spectrum here can be defined as those values of $\xi \notin[-1,1]$ such that

$$
\begin{equation*}
\boldsymbol{A}(\xi)=0 . \tag{15}
\end{equation*}
$$

## BASIC IDENTITIES

We now follow a procedure reported by Inönü' and Garcia and Siewert ${ }^{2}$ for the one-group model and develop for the considered multi-group model a set of identities that provides the basis of our computational method for establishing the discrete spectrum.

We define, for $\xi \notin[-1,1]$,

$$
\begin{equation*}
\mathbf{Q}_{l}(\xi)=\int_{-1}^{1}(\mu \mathbf{I}-\xi \Sigma)^{-1} P_{l}(\mu) \mathrm{d} \mu \tag{16}
\end{equation*}
$$

so that we can write the $\boldsymbol{\Lambda}$ matrix as

$$
\begin{equation*}
\boldsymbol{A}(\xi)=\mathbf{I}+\xi \sum_{l=0}^{L} \mathbf{Q}_{l}(\xi) \mathbf{C}_{l} \mathbf{G}_{l}(\xi) \tag{17}
\end{equation*}
$$

Multiplying equation (16) by $(2 l+1) \xi$ and using partial-fraction analysis and the recursion formula

$$
\begin{equation*}
(2 l+1) \mu P_{l}(\mu)=(l+1) P_{l+1}(\mu)+l P_{l-1}(\mu), \tag{18}
\end{equation*}
$$

we find that the $\mathbf{Q}_{i}(\xi)$ satisfy the recursion formula

$$
\begin{equation*}
(2 l+1) \xi \Sigma \mathbf{Q}_{l}(\xi)=(l+1) \mathbf{Q}_{l+1}(\xi)+l \mathbf{Q}_{l-1}(\xi)-2 \delta_{0 . l} \mathbf{I} . \tag{19}
\end{equation*}
$$

We can now multiply equation (10) on the left by $\mathbf{Q}_{i}(\xi)$, multiply equation (19) on the right by $\mathbf{G}_{l}(\xi)$, subtract one of the two resulting equations from the other and then sum the resulting equation from $l=0$ to $l=L$ to find, after noting equation (17),

$$
\begin{equation*}
\boldsymbol{\Lambda}(\xi)=\frac{1}{2}(L+1)\left[\mathbf{Q}_{L+1}(\xi) \mathbf{G}_{L}(\xi)-\mathbf{Q}_{L}(\xi) \mathbf{G}_{L+1}(\xi)\right] . \tag{20}
\end{equation*}
$$

Introducing matrices $\Pi_{l}(\xi)=\operatorname{diag}\left\{P_{l}\left(\sigma_{1} \xi\right), P_{l}\left(\sigma_{2} \xi\right), \ldots, P_{l}\left(\sigma_{M} \xi\right)\right\}$ and noting equation (18), we now write

$$
\begin{equation*}
(2 l+1) \xi \Sigma \Pi_{l}(\xi)=(l+1) \Pi_{l+1}(\xi)+l \Pi_{l-1}(\xi) . \tag{21}
\end{equation*}
$$

Now multiplying equation (19) by $\boldsymbol{\Pi}_{l}(\xi)$, multiplying equation (21) by $\mathbf{Q}_{l}(\xi)$, taking the difference and then summing over $l$, we find the identity

$$
\begin{equation*}
\mathbf{I}=\frac{1}{2}(L+1)\left[\mathbf{Q}_{L+1}(\xi) \boldsymbol{\Pi}_{L}(\xi)-\mathbf{Q}_{L}(\xi) \boldsymbol{\Pi}_{L+1}(\xi)\right] . \tag{22}
\end{equation*}
$$

In a similar manner we can find from equations (10) and (21) that

$$
\begin{equation*}
\xi \sum_{l=0}^{L} \boldsymbol{\Pi}_{l}(\xi) \mathbf{C}_{l} \mathbf{G}_{l}(\xi)=\frac{1}{2}(L+1)\left[\boldsymbol{\Pi}_{L+1}(\xi) \mathbf{G}_{L}(\xi)-\boldsymbol{\Pi}_{L}(\xi) \mathbf{G}_{L+1}(\xi)\right] \tag{23}
\end{equation*}
$$

Finally we multiply equation (20) by $\boldsymbol{\Pi}_{L+1}(\xi)$ and use equations (22) and (23) to obtain

$$
\begin{equation*}
\boldsymbol{\Pi}_{L+1}(\xi) \boldsymbol{\Lambda}(\xi)=\mathbf{G}_{L+1}(\xi)+\xi \mathbf{Q}_{L+1}(\xi) \sum_{l=0}^{L} \boldsymbol{\Pi}_{l}(\xi) \mathbf{C}_{l} \mathbf{G}_{l}(\xi) \tag{24}
\end{equation*}
$$

If we consider that $\mathbf{C}_{l}=\mathbf{0}$ for $l>L$, we can write, for $\xi \notin[-1,1]$,

$$
\begin{equation*}
\boldsymbol{\Lambda}(\xi)=\boldsymbol{\Pi}_{N+1}^{-1}(\xi)\left[\mathbf{G}_{N+1}(\xi)+\xi \mathbf{Q}_{N+1}(\xi) \sum_{l=0}^{L} \boldsymbol{\Pi}_{l}(\xi) \mathbf{C}_{l} \mathbf{G}_{l}(\xi)\right] \tag{25}
\end{equation*}
$$

for any $N \geqslant L$. In particular since Robin ${ }^{3}$ has shown that the Legendre function of the second kind

$$
\begin{equation*}
Q_{l}(\xi)=\frac{1}{2} \int_{-1}^{1} P_{l}(\mu) \frac{\mathrm{d} \mu}{\xi-\mu} \tag{26}
\end{equation*}
$$

vanishes as $l \rightarrow \infty$ for all $\xi \notin[-1,1]$ we conclude from equations (16) and (25) that

$$
\begin{equation*}
\boldsymbol{\Lambda}(\xi)=\lim _{N \rightarrow \infty} \boldsymbol{\Pi}_{N+1}^{-1}(\xi) \mathbf{G}_{N+1}(\xi), \quad \xi \notin[-1,1] . \tag{27}
\end{equation*}
$$

It thus follows that the zeros of $\operatorname{det} \mathbf{G}_{N+1}(\xi)$ that lie outside the interval [ $\left.-1,1\right]$ will approximate the desired discrete spectrum with better and better accuracy as $N$ increases.

## A COMPUTATIONAL METHOD

As we wish to approximate our exact problem

$$
\begin{equation*}
\boldsymbol{\Lambda}(\xi) \mathbf{M}(\xi)=\mathbf{0} \tag{28}
\end{equation*}
$$

by

$$
\begin{equation*}
\mathbf{G}_{N+1}(\xi) \mathbf{N}(\xi)=\mathbf{0}, \tag{29}
\end{equation*}
$$

we now let

$$
\begin{equation*}
\mathbf{T}_{l}(\xi)=\mathbf{G}_{l}(\xi) \mathbf{N}(\xi), \tag{30}
\end{equation*}
$$

for $l=0,1,2, \ldots, N$, and multiply equation (10) by $\mathbf{N}(\xi)$ to obtain

$$
\begin{equation*}
l \mathbf{h}_{l}^{-1} \mathbf{T}_{l-1}(\xi)+(l+1) \mathbf{h}_{l}^{-1} \mathbf{T}_{l+1}(\xi)=\xi \mathbf{T}_{l}(\xi) \tag{31}
\end{equation*}
$$

for $l=0,1, \ldots, N$. Equation (31) along with the termination condition $\mathbf{T}_{N+1}(\xi)=\mathbf{0}$ can be
expressed as an eigenvalue problem for the $M(N+1)$ zeros of $\operatorname{det} \mathbf{G}_{N+1}(\xi)$. However, we prefer first to consider $N$ to be odd and to eliminate the odd-order Ts in equation (31); we find, for $l=0,2,4, \ldots, N-1$, that

$$
\begin{equation*}
\mathbf{X}_{l} \mathbf{T}_{l-2}(\xi)+\mathbf{Y}_{l} \mathbf{T}_{l}(\xi)+\mathbf{Z}_{l} \mathbf{T}_{l+2}(\xi)=\xi^{2} \mathbf{T}_{l}(\xi) \tag{32}
\end{equation*}
$$

where

$$
\begin{align*}
& \mathbf{X}_{l}=l(l-1) \mathbf{h}_{l}^{-1} \mathbf{h}_{l-1}^{-1}  \tag{33a}\\
& \mathbf{Y}_{l}=l^{2} \mathbf{h}_{l}^{-1} \mathbf{h}_{i-1}^{-1}+(l+1)^{2} \mathbf{h}_{l}^{-i} \mathbf{h}_{l+1}^{-1} \tag{33b}
\end{align*}
$$

and

$$
\begin{equation*}
\mathbf{Z}_{l}=(l+1)(l+2) \mathbf{h}_{l}^{-1} \mathbf{h}_{l+1}^{-1} \tag{33c}
\end{equation*}
$$

Equation (32) and the truncation condition $\mathrm{T}_{N+1}(\xi)=0$ can now be expressed as the eigenvalue problem

$$
\begin{equation*}
\mathbf{A X}=\xi^{2} \mathbf{X} \tag{34}
\end{equation*}
$$

where

$$
\mathbf{A}=\left[\begin{array}{lllllll}
\mathbf{Y}_{0} & \mathbf{Z}_{0} & & & & &  \tag{35}\\
\mathbf{X}_{2} & \mathbf{Y}_{2} & \mathbf{Z}_{2} & & & & \\
& \cdot & \therefore & \therefore & \ddots & & \\
& & & \dot{\mathbf{X}}_{N-3} & . & & \\
& & & \mathbf{Y}_{N-3} & \mathbf{Z}_{N} \\
& & & & \mathbf{X}_{N-1} & \mathbf{Y}_{N-1}
\end{array}\right]
$$

is $M(N+1) / 2$ square and the $\mathbf{X}$ vector has entries $\mathbf{T}_{0}(\xi), \mathbf{T}_{2}(\xi), \ldots, \mathbf{T}_{N-1}(\xi)$. It follows that the $J=M(N+1) / 2$ eigenvalues of $\mathbf{A}$ provide the squares of the $J \pm$ pairs of zeros of $\operatorname{det} \mathbf{G}_{N+1}(\xi)$.

## NUMERICAL RESULTS

Having generalized previous works, ${ }^{4-7}$ on scalar problems, and works on a four-vector polarization problem in radiative transfer ${ }^{8,9}$ to the case of multi-group transport theory, we now report some numerical results that indicate the accuracy with which the zeros of $\operatorname{det} \mathbf{G}_{N+1}(\xi)$, $\xi \notin[-1,1]$, approximate the discrete spectrum defined by $\operatorname{det} \boldsymbol{\Lambda}(\xi)=0, \xi \notin[-1,1]$.

Although the matrix A defined by equation (35) is banded (and sparse for $N \gg M$ ) we have not made use of this structure here. We have simply used the driver program RG in the EISPACK collection ${ }^{10,11}$ to compute the eigenvalues.

For our first set of numerical examples we consider the four $L=0$ data cases that were defined by Forster ${ }^{12}$ and used by Kriese, Siewert and Yener ${ }^{13}$ for two-group critical calculations in neutron transport theory. Thus we write

$$
\begin{align*}
& \left(\mathbf{T}_{0}\right)_{11}=\frac{1}{2}\left[\sigma_{11 s}+(1-\chi) \bar{v}_{1} \sigma_{1 f}\right]  \tag{36a}\\
& \left(\mathbf{T}_{0}\right)_{12}=\frac{1}{2}\left[\sigma_{12 s}+(1-\chi) \bar{v}_{2} \sigma_{2 f}\right]  \tag{36b}\\
& \left(\mathbf{T}_{0}\right)_{21}=\frac{1}{2} \chi \bar{v}_{1} \sigma_{1 f} \tag{36c}
\end{align*}
$$

and

$$
\begin{equation*}
\left(\mathbf{T}_{0}\right)_{22}=\frac{1}{2}\left[\sigma_{22 s}+\chi^{\bar{v}_{2}} \sigma_{2 f}\right] \tag{36~d}
\end{equation*}
$$

and use the data in Table 1 to define the $S$ and $T_{0}$ matrices basic to equation (1). In Table 2 we list the exact results ${ }^{13}$ for the discrete eigenvalues for these four cases and the values of $N$ we require here to duplicate, to the given degree of accuracy, these discrete eigenvalues.

To have a more challenging test case we considered the analytical 20 -group model, with $L=10$, that was used by Garcia and Siewert. ${ }^{14}$ This 20-group model, defined in Ref. [14], was used for a

Table 1. Two-group macroscopic cross sections (in $\mathrm{cm}^{-1}$ )

| Table 1. Two-group macroscopic cross sections (in $\mathrm{cm}^{-1}$ ) |  |  |  |  |  |  |  |  |
| :---: | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| Case | $s_{1}$ | $\sigma_{11 s}$ | $\overline{\mathrm{v}}_{1} \sigma_{1 f}$ | $\sigma_{12 \mathrm{~s}}$ | $s_{2}$ | $\sigma_{22 \mathrm{~s}}$ | $\bar{v}_{2} \sigma_{2 f}$ | $\chi$ |
| I | 0.54628 | 0.4241 | 0.2425 | 0.0045552 | 0.33588 | 0.3198 | 0.0070425 | 1.0 |
| II | 2.52025 | 2.44383 | 0.12658 | 0.029227 | 0.65696 | 0.62568 | 0.002621 | 1.0 |
| III | 0.3456 | 0.26304 | 0.1728 | 0.072 | 0.216 | 0.07824 | 0.167184 | 0.575 |
| IV | 0.336 | 0.23616 | 0.2503392 | 0.0432 | 0.2208 | 0.0792 | 0.29016 | 0.575 |

Table 2. Discrete eigenvalues

| Case | Eigenvalue | $N$ |
| :---: | :--- | ---: |
| I | $i 1.81477(2)$ | 5 |
| II | $i 3.54785$ | 5 |
| III | $i 6.72584(-1)$ | 11 |
| IV | $i 4.80216(-1)$ | 15 |

radiation shielding study, and so there is no fission nor any up-scattering in the model. For this problem there is only one discrete eigenvalue $\xi \notin[-1,1]$; for $N=69$ we obtained a result that agreed with the published result to nine significant figures.

To conclude we note that the A matrix defined by equation (35) can, especially for many-group problems, become very large as $N$ increases. It is clear that there can be cases where the size of A becomes unmanageable before $N$ is sufficiently large so as to yield very accurate, say 10 figures, results for the desired eigenvalues. For these cases some alternative computational method, e.g. Newton's method applied to $\Lambda(\xi)$, may be required.

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