

The temperature-jump problem for a variable collision frequency model

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An analytical version of the discrete-ordinates method is used here in the field of rarefied-gas dynamics to solve a version of the temperature-jump problem that is based on a linearized, variable collision frequency model of the Boltzmann equation. In addition to a complete development of the discrete-ordinates method for the application considered, the computational algorithm is implemented to yield accurate numerical results for three specific cases: the classical BGK model, the Williams model (the collision frequency is proportional to the magnitude of the velocity), and the rigid-sphere model. © 2002 American Institute of Physics. [DOI: 10.1063/1.1416192]

I. INTRODUCTION

The state of a gas can be described mathematically by a distribution function that satisfies the nonlinear Boltzmann equation.¹⁻³ While, for example, Monte Carlo methods and computationally intensive iterative methods are ways of attempting to extract some physical information from the nonlinear Boltzmann equation, another approach that can be used when the density of particles is small (rarefied-gas dynamics) is to approximate the nonlinear Boltzmann equation by a so-called model equation.⁴ In recent years, we have seen an increased interest in the general area of rarefied-gas dynamics essentially because of applications to small-scale problems (for example, as related to micro-machines and high-speed disk drives) where the Boltzmann equation or a model equation is required in order to describe well gas-flow and heat-flow mechanisms. In this work, we take advantage of some recent mathematical and numerical improvements in the discrete-ordinates method in order to establish a series of high-quality results for the temperature-jump problem as based on a generalization of the standard BGK model.

Although the so-called BGK model⁵ introduced by Bhatnagar, Gross, and Krook has been the focus of the vast majority of mathematical studies in the general area of rarefied-gas dynamics, there exist numerous models that have been used to try to improve on the simplest form of the BGK model. One such approach⁶⁻¹¹ is based on the variable collision frequency model (sometimes referred to as the generalized BGK model) since it has been shown⁹ better able to support some experimental observations. In a recent work¹²

the variable collision frequency model was used to solve the classical Kramers' problem,³ and so in this work we extend our use¹³ of the discrete-ordinates method¹⁴ to solve the temperature-jump problem¹⁵ for a general version of a linearized, variable collision frequency model of the Boltzmann equation. Here we base our notation on Williams' book;³ however, the papers of Cercignani⁷ and Loyalka and Ferziger⁸ are the ones we consider to be the defining works on this subject of the variable collision frequency model. It therefore seems reasonable to refer to the general model equation used in this work as the CLF equation and to consider the BGK model (constant collision frequency), the Williams model (the collision frequency is proportional to the particle speed), and the rigid-sphere model as special cases that correspond to certain choices of the collision frequency.

To introduce the mathematical statement of the problem to be solved, we follow Williams³ and consider the defining balance equation to be

$$c\mu \frac{\partial}{\partial x} h(x, \mathbf{c}) + V(c)h(x, \mathbf{c}) = \int_0^\infty \int_{-1}^1 \int_0^{2\pi} c'^2 e^{-c'^2} K(\mathbf{c}; \mathbf{c}') h(x, \mathbf{c}') d\chi' d\mu' dc'. \quad (1)$$

Here

$$h(x, \mathbf{c}) \Rightarrow h(x, c, \mu, \chi) \quad (2)$$

and

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$$K(\mathbf{c}; \mathbf{c}') = \frac{1}{4\pi} V(c)V(c') [\gamma_0 + \gamma_1 \mathbf{c} \cdot \mathbf{c}' + \gamma_2 (c^2 - \omega)] \times (c'^2 - \omega), \tag{3}$$

where

$$\gamma_0 = \frac{1}{V_0}, \tag{4a}$$

$$\gamma_1 = \frac{3}{V_2}, \tag{4b}$$

$$\gamma_2 = \frac{V_0}{V_0 V_4 - V_2^2}, \tag{4c}$$

and

$$\omega = \frac{V_2}{V_0} \tag{4d}$$

with

$$V_n = \int_0^\infty V(c) c^{n+2} e^{-c^2} dc. \tag{5}$$

In addition, c is used, with dimensionless units, to denote the magnitude of the particle velocity vector \mathbf{c} , $x \geq 0$ is the spatial variable that measures (in dimensionless units) the distance from the wall, $V(c)$ is the collision frequency, and μ and χ are the two angular variables that define the direction (relative to the positive x axis) of the velocity. In addition to Eq. (1) we consider the boundary condition at the wall written as

$$h(0, c, \mu, \chi) - (1 - \alpha)h(0, c, -\mu, \chi + \pi) - (\mathcal{I}h)(0) = 0 \tag{6a}$$

for $\mu \in (0, 1]$, $c \in [0, \infty)$, and $\chi \in [0, \pi]$ and

$$h(0, c, \mu, \chi) - (1 - \alpha)h(0, c, -\mu, \chi - \pi) - (\mathcal{I}h)(0) = 0 \tag{6b}$$

for $\mu \in (0, 1]$, $c \in [0, \infty)$, and $\chi \in [\pi, 2\pi]$. Here

$$(\mathcal{I}h)(0) = \frac{2\alpha}{\pi} \int_0^\infty \int_0^1 \int_0^{2\pi} c'^3 e^{-c'^2} h(0, c', -\mu', \chi') \times \mu' d\chi' d\mu' dc' \tag{7}$$

and $\alpha \in (0, 1]$ is the accommodation coefficient. Our basic unknown $h(x, \mathbf{c})$ is the perturbation from an initial Maxwellian distribution that, due to the presence of the wall, is a component of the particle distribution function. In regard to Eqs. (6), we note that some fraction $1 - \alpha$ of the particles is reflected specularly and that the remaining fraction α is reflected diffusely. In other words, the wall acts somewhat like a mirror and at the same time appears to absorb some of the particles and then re-emit them isotropically. Because there is no loss or supply of particles due to the presence of the wall, the boundary condition can be thought of as conservative. In addition to the boundary condition given by Eqs. (6), we note that, as will be discussed later, we must also impose a condition on $h(x, \mathbf{c})$ as x tends to infinity.

II. QUANTITIES OF INTEREST

While our problem is defined in terms of the basic unknown $h(x, \mathbf{c})$, we require only two elementary integrals of $h(x, \mathbf{c})$. To be clear, we note that here we seek the temperature and density perturbations⁸ defined by

$$N(x) = \frac{1}{\pi^{3/2}} \int_0^\infty \int_{-1}^1 \int_0^{2\pi} c^2 e^{-c^2} h(x, c, \mu, \chi) d\chi d\mu dc \tag{8}$$

and

$$T(x) = \frac{2}{3\pi^{3/2}} \int_0^\infty \int_{-1}^1 \int_0^{2\pi} c^2 e^{-c^2} (c^2 - 3/2) \times h(x, c, \mu, \chi) d\chi d\mu dc, \tag{9}$$

or

$$N(x) = \frac{2}{\pi^{1/2}} \int_0^\infty \int_{-1}^1 c^2 e^{-c^2} \phi(x, c, \mu) d\mu dc \tag{10}$$

and

$$T(x) = \frac{4}{3\pi^{1/2}} \int_0^\infty \int_{-1}^1 c^2 e^{-c^2} (c^2 - 3/2) \phi(x, c, \mu) d\mu dc, \tag{11}$$

where

$$\phi(x, c, \mu) = \frac{1}{2\pi} \int_0^{2\pi} h(x, c, \mu, \chi) d\chi \tag{12}$$

is an azimuthal average. We can integrate Eqs. (1) and (6) over χ to find

$$c\mu \frac{\partial}{\partial x} \phi(x, c, \mu) + V(c) \phi(x, c, \mu) = \int_0^\infty \int_{-1}^1 c'^2 e^{-c'^2} K(c, \mu; c', \mu') \phi(x, c', \mu') d\mu' dc', \tag{13}$$

for $x > 0$, $\mu \in [-1, 1]$ and $c \in [0, \infty)$, and

$$\phi(0, c, \mu) - (1 - \alpha)\phi(0, c, -\mu) - 4\alpha \int_0^\infty \int_0^1 c'^3 e^{-c'^2} \phi(0, c', -\mu') \mu' d\mu' dc' = 0, \tag{14}$$

for $\mu \in (0, 1]$ and $c \in [0, \infty)$. Here

$$K(c, \mu; c', \mu') = \frac{1}{2} V(c)V(c') [\gamma_0 + \gamma_1 c\mu c' \mu' + \gamma_2 (c^2 - \omega)(c'^2 - \omega)]. \tag{15}$$

As Eqs. (1) and (6) are homogeneous, we must specify a driving term for the temperature-jump problem. We do this implicitly by requiring that $h(x, c, \mu, \xi)$ diverge as x tends to infinity. More specifically, we impose the condition that the temperature perturbation satisfies the Welander condition¹⁶

$$\lim_{x \rightarrow \infty} \frac{d}{dx} T(x) = K, \tag{16}$$

where K is considered specified. Now let

$$V(c) = \sigma \eta(c), \tag{17}$$

where σ is a scale factor to be defined later and where $\eta(c)$ is a ‘‘shape factor’’ used to define the variable collision frequency. We also introduce

$$\tau = \sigma x \tag{18a}$$

and

$$Y(\tau, c, \mu) = \phi(\tau/\sigma, c, \mu) \tag{18b}$$

and rewrite our problem as

$$c\mu \frac{\partial}{\partial \tau} Y(\tau, c, \mu) + \eta(c)Y(\tau, c, \mu) = \int_0^\infty \int_{-1}^1 c'^2 e^{-c'^2} F(c, \mu; c', \mu') Y(\tau, c', \mu') d\mu' dc', \tag{19}$$

for $\tau > 0$, $\mu \in [-1, 1]$ and $c \in [0, \infty)$, and

$$Y(0, c, \mu) - (1 - \alpha)Y(0, c, -\mu) - 4\alpha \int_0^\infty \int_0^1 c'^3 e^{-c'^2} Y(0, c', -\mu') \mu' d\mu' dc' = 0, \tag{20}$$

for $\mu \in (0, 1]$ and $c \in [0, \infty)$. Here

$$F(c, \mu; c', \mu') = \frac{1}{2} \eta(c) \eta(c') [\beta_0 + \beta_1 c \mu c' \mu' + \beta_2 (c^2 - \omega)(c'^2 - \omega)], \tag{21}$$

where

$$\beta_0 = \frac{1}{\eta_2}, \tag{22a}$$

$$\beta_1 = \frac{3}{\eta_4}, \tag{22b}$$

$$\beta_2 = \frac{\eta_2}{\eta_2 \eta_6 - \eta_4^2} \tag{22c}$$

and

$$\omega = \frac{\eta_4}{\eta_2} \tag{22d}$$

with

$$\eta_n = \int_0^\infty \eta(c) c^n e^{-c^2} dc. \tag{23}$$

Now we let

$$T_*(\tau) = T(\tau/\sigma) \text{ and } N_*(\tau) = N(\tau/\sigma), \tag{24}$$

and so we can write

$$N_*(\tau) = \frac{2}{\pi^{1/2}} \int_0^\infty \int_{-1}^1 c^2 e^{-c^2} Y(\tau, c, \mu) d\mu dc \tag{25}$$

and

$$T_*(\tau) = \frac{4}{3\pi^{1/2}} \int_0^\infty \int_{-1}^1 c^2 e^{-c^2} (c^2 - 3/2) Y(\tau, c, \mu) d\mu dc. \tag{26}$$

Finally to complete the definition of our problem, we rewrite Eq. (16) as

$$\lim_{\tau \rightarrow \infty} \frac{d}{d\tau} T_*(\tau) = \frac{K}{\sigma}. \tag{27}$$

At this point we note that

$$Z_a(\tau, c, \mu) = (c^2 - 5/2)[\tau - c\mu/\eta(c)] \tag{28}$$

is a solution of Eq. (19) that is linear in τ , and so we choose to decompose the required solution into a part that has the desired behavior as τ tends to infinity and a part that is bounded. We therefore write

$$Y(\tau, c, \mu) = \frac{K}{\sigma} [Z(\tau, c, \mu) + Z_a(\tau, c, \mu)] \tag{29}$$

and find from Eqs. (25) and (26), after using Eqs. (28) and (29), results for the density and temperature perturbations expressed in terms of the bounded component $Z(\tau, c, \mu)$, viz.

$$N_*(\tau) = (K/\sigma) \left[-\tau + \frac{2}{\pi^{1/2}} \times \int_0^\infty \int_{-1}^1 c^2 e^{-c^2} Z(\tau, c, \mu) d\mu dc \right] \tag{30}$$

and

$$T_*(\tau) = (K/\sigma) \left[\tau + \frac{4}{3\pi^{1/2}} \int_0^\infty \int_{-1}^1 c^2 e^{-c^2} (c^2 - 3/2) \times Z(\tau, c, \mu) d\mu dc \right]. \tag{31}$$

It follows now that we seek a solution $Z(\tau, c, \mu)$ that is bounded as τ tends to infinity and that satisfies

$$c\mu \frac{\partial}{\partial \tau} Z(\tau, c, \mu) + \eta(c)Z(\tau, c, \mu) = \int_0^\infty \int_{-1}^1 c'^2 e^{-c'^2} F(c, \mu; c', \mu') Z(\tau, c', \mu') d\mu' dc', \tag{32}$$

for $\tau > 0$, $\mu \in [-1, 1]$ and $c \in [0, \infty)$, and

$$Z(0, c, \mu) - (1 - \alpha)Z(0, c, -\mu) - 4\alpha \int_0^\infty \int_0^1 c'^3 e^{-c'^2} Z(0, c', -\mu') \mu' d\mu' dc' = R(c, \mu), \tag{33}$$

for $\mu \in (0, 1]$ and $c \in [0, \infty)$. Here

$$R(c, \mu) = (2 - \alpha)(c^2 - 5/2) \frac{c\mu}{\eta(c)} + \frac{4\alpha}{3} \Gamma, \tag{34}$$

where

$$\Gamma = \int_0^\infty \frac{c^4}{\eta(c)} e^{-c^2} (c^2 - 5/2) dc. \tag{35}$$

Our basic statement of the problem to be solved is now complete, and so we proceed with our solution; however, before making use of our version of the discrete-ordinates method, we introduce some elementary transformations that will facilitate the development of the final results.

III. BASIC TRANSFORMATIONS

Rather than deal explicitly with Eqs. (32) and (33), we choose to follow Busbridge¹⁷ and to introduce the convenient change of variables

$$\xi = \frac{c\mu}{\eta(c)} \tag{36a}$$

and

$$\gamma = \sup\{c/\eta(c)\}. \tag{36b}$$

And so now if we go back to Eq. (32) and introduce the decomposition

$$Z[\tau, c, \xi\eta(c)/c] = G_1(\tau, \xi) + \xi\eta(c)G_2(\tau, \xi) + (c^2 - \omega)G_3(\tau, \xi) \tag{37}$$

we find, after an interchange of orders of integration,

$$\xi \frac{\partial}{\partial \tau} G_i(\tau, \xi) + G_i(\tau, \xi) = \int_{-\gamma}^{\gamma} [\psi_{i,1}(\xi')G_1(\tau, \xi') + \psi_{i,2}(\xi')G_2(\tau, \xi') + \psi_{i,3}(\xi')G_3(\tau, \xi')]d\xi' \tag{38}$$

for $i = 1, 2, 3$. Here

$$\psi_{1,1}(\xi) = \frac{\beta_0}{2} \int_{M_\xi} ce^{-c^2} \eta^2(c)dc, \tag{39a}$$

$$\psi_{1,2}(\xi) = \frac{\beta_0\xi}{2} \int_{M_\xi} ce^{-c^2} \eta^3(c)dc, \tag{39b}$$

$$\psi_{1,3}(\xi) = \frac{\beta_0}{2} \int_{M_\xi} ce^{-c^2} \eta^2(c)(c^2 - \omega)dc, \tag{39c}$$

$$\psi_{2,1}(\xi) = \frac{\beta_1\xi}{2} \int_{M_\xi} ce^{-c^2} \eta^3(c)dc, \tag{39d}$$

$$\psi_{2,2}(\xi) = \frac{\beta_1\xi^2}{2} \int_{M_\xi} ce^{-c^2} \eta^4(c)dc, \tag{39e}$$

$$\psi_{2,3}(\xi) = \frac{\beta_1\xi}{2} \int_{M_\xi} ce^{-c^2} \eta^3(c)(c^2 - \omega)dc, \tag{39f}$$

$$\psi_{3,1}(\xi) = \frac{\beta_2}{2} \int_{M_\xi} ce^{-c^2} \eta^2(c)(c^2 - \omega)dc, \tag{39g}$$

$$\psi_{3,2}(\xi) = \frac{\beta_2\xi}{2} \int_{M_\xi} ce^{-c^2} \eta^3(c)(c^2 - \omega)dc \tag{39h}$$

and

$$\psi_{3,3}(\xi) = \frac{\beta_2}{2} \int_{M_\xi} ce^{-c^2} \eta^2(c)(c^2 - \omega)^2dc, \tag{39i}$$

where

$$c \in M_\xi \text{ if } \frac{\eta(c)|\xi|}{c} \leq 1. \tag{40}$$

In regard to boundary conditions, we substitute Eq. (37) into Eq. (33) to obtain

$$G_1(0, \xi) - (1 - \alpha)G_1(0, -\xi) - \Delta = \frac{4\alpha}{3}\Gamma + (2 - \alpha)(\omega - 5/2)\xi, \tag{41a}$$

$$G_2(0, \xi) + (1 - \alpha)G_2(0, -\xi) = 0, \tag{41b}$$

and

$$G_3(0, \xi) - (1 - \alpha)G_3(0, -\xi) = (2 - \alpha)\xi \tag{41c}$$

for $\xi \in (0, \gamma]$. Here the diffuse term in Eq. (41a) is given by

$$\Delta = \frac{8\alpha}{\beta_0} \int_0^\gamma [\psi_{1,1}(\xi)G_1(0, -\xi) - \psi_{1,2}(\xi)G_2(0, -\xi) + \psi_{1,3}(\xi)G_3(0, -\xi)]\xi d\xi. \tag{42}$$

We now introduce the vector-valued function $\mathbf{G}(\tau, \xi)$, with components $G_i(\tau, \xi)$, $i = 1, 2, 3$, and write Eq. (38) as

$$\xi \frac{\partial}{\partial \tau} \mathbf{G}(\tau, \xi) + \mathbf{G}(\tau, \xi) = \int_{-\gamma}^{\gamma} \mathbf{\Psi}(\xi')\mathbf{G}(\tau, \xi')d\xi', \tag{43}$$

where the 3×3 matrix $\mathbf{\Psi}(\xi)$ has components $\psi_{i,j}(\xi)$. To have our boundary conditions in vector form, we rewrite Eqs. (41) as

$$\mathbf{G}(0, \xi) - (1 - \alpha)\mathbf{S}\mathbf{G}(0, -\xi) - 2\alpha \int_0^\gamma \mathbf{Y}(\xi')\mathbf{G}(0, -\xi')\xi' d\xi' = \mathbf{R}(\xi) \tag{44}$$

for $\xi \in (0, \gamma]$. Here

$$\mathbf{S} = \text{diag}\{1, -1, 1\}, \tag{45}$$

$$\mathbf{Y}(\xi) = \frac{4}{\beta_0} \begin{bmatrix} \psi_{1,1}(\xi) & -\psi_{1,2}(\xi) & \psi_{1,3}(\xi) \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \tag{46}$$

and

$$\mathbf{R}(\xi) = \begin{bmatrix} (2 - \alpha)(\omega - 5/2)\xi + (4/3)\alpha\Gamma \\ 0 \\ (2 - \alpha)\xi \end{bmatrix}. \tag{47}$$

And so we seek a bounded (as $\tau \rightarrow \infty$) solution of Eq. (43) that satisfies Eq. (44). Of course, once we have solved the \mathbf{G} problem, we can use Eq. (37) to rewrite Eqs. (30) and (31) as

$$N_*(\tau) = (K/\sigma) \left\{ -\tau + \frac{1}{\pi^{1/2}} \int_{-\gamma}^{\gamma} [n_1(\xi)G_1(\tau, \xi) + n_2(\xi)G_2(\tau, \xi) + n_3(\xi)G_3(\tau, \xi)]d\xi \right\} \tag{48}$$

and

$$T_*(\tau) = (K/\sigma) \left\{ \tau + \frac{2}{3\pi^{1/2}} \int_{-\gamma}^{\gamma} [t_1(\xi)G_1(\tau, \xi) + t_2(\xi)G_2(\tau, \xi) + t_3(\xi)G_3(\tau, \xi)] d\xi \right\}, \quad (49)$$

where

$$n_1(\xi) = 2 \int_{M_\xi} c e^{-c^2} \eta(c) dc, \quad (50a)$$

$$n_2(\xi) = 2\xi \int_{M_\xi} c e^{-c^2} \eta^2(c) dc, \quad (50b)$$

and

$$n_3(\xi) = 2 \int_{M_\xi} c e^{-c^2} \eta(c) (c^2 - \omega) dc, \quad (50c)$$

and also where

$$t_1(\xi) = 2 \int_{M_\xi} c e^{-c^2} \eta(c) (c^2 - 3/2) dc, \quad (51a)$$

$$t_2(\xi) = 2\xi \int_{M_\xi} c e^{-c^2} \eta^2(c) (c^2 - 3/2) dc, \quad (51b)$$

and

$$t_3(\xi) = 2 \int_{M_\xi} c e^{-c^2} \eta(c) (c^2 - \omega) (c^2 - 3/2) dc. \quad (51c)$$

It is clear that the scale factor σ will have a fundamental effect on our reported numerical results, and since there already exist various possibilities in the literature concerning the definition of an appropriate mean-free path, we elect here to use one of Loyalka's choices⁹ for scaling our results. We therefore define

$$\sigma = \epsilon_t = \frac{16}{15} \pi^{-1/2} \int_0^\infty \eta^{-1}(c) c^4 e^{-c^2} (c^2 - 5/2)^2 dc \quad (52)$$

for all models we consider. As noted by Loyalka,⁹ the use of $\sigma = \epsilon_t$ corresponds to measuring our spatial variable x in terms of a mean-free path l_t that is defined in terms of the thermal conductivity.

IV. THE DISCRETE-ORDINATES SOLUTION

We note first of all that the characteristic matrix $\Psi(\xi)$, as defined by Eqs. (39), is not symmetric. We note also that $\Psi(\xi) \neq \Psi(-\xi)$, and so we write our discrete-ordinates version of Eq. (43) as

$$\pm \xi_i \frac{d}{d\tau} \mathbf{G}(\tau, \pm \xi_i) + \mathbf{G}(\tau, \pm \xi_i) = \sum_{k=1}^N w_k [\Psi(\xi_k) \mathbf{G}(\tau, \xi_k) + \Psi(-\xi_k) \mathbf{G}(\tau, -\xi_k)] \quad (53)$$

for $i = 1, 2, \dots, N$. In writing Eqs. (53) as we have, we clearly are considering that the N quadrature points $\{\xi_k\}$ and the N weights $\{w_k\}$ are defined for use on the integration interval $[0, \gamma]$. We note that it is to this feature of using a "half-

range" quadrature scheme that we partially attribute the especially good accuracy we have obtained from the solution reported here. Continuing, we substitute

$$\mathbf{G}(\tau, \pm \xi_i) = \Phi(\nu, \pm \xi_i) e^{-\tau/\nu} \quad (54)$$

into Eqs. (53) to find

$$(\nu \mp \xi_i) \Phi(\nu, \pm \xi_i) = \nu \sum_{k=1}^N w_k [\Psi(\xi_k) \Phi(\nu, \xi_k) + \Psi(-\xi_k) \Phi(\nu, -\xi_k)] \quad (55)$$

for $i = 1, 2, \dots, N$. Now let

$$\Phi_+(\nu) = [\Phi^T(\nu, \xi_1) \quad \Phi^T(\nu, \xi_2) \quad \dots \quad \Phi^T(\nu, \xi_N)]^T, \quad (56a)$$

$$\Phi_-(\nu) = [\Phi^T(\nu, -\xi_1) \quad \Phi^T(\nu, -\xi_2) \quad \dots \quad \Phi^T(\nu, -\xi_N)]^T, \quad (56b)$$

and

$$\mathbf{M} = \text{diag}\{\xi_1 \mathbf{I}, \xi_2 \mathbf{I}, \dots, \xi_N \mathbf{I}\}, \quad (57)$$

where \mathbf{I} is the 3×3 identity matrix. In addition we let \mathbf{W}_+ and \mathbf{W}_- denote $3N \times 3N$ matrices each $3 \times 3N$ row of which is, respectively,

$$\mathbf{R}_+ = [w_1 \Psi(\xi_1) \quad w_2 \Psi(\xi_2) \quad \dots \quad w_N \Psi(\xi_N)] \quad (58)$$

and

$$\mathbf{R}_- = [w_1 \Psi(-\xi_1) \quad w_2 \Psi(-\xi_2) \quad \dots \quad w_N \Psi(-\xi_N)] \quad (59)$$

so that we can write Eqs. (55) as

$$\nu \Phi_+(\nu) - \mathbf{M} \Phi_+(\nu) = \nu [\mathbf{W}_+ \Phi_+(\nu) + \mathbf{W}_- \Phi_-(\nu)] \quad (60a)$$

and

$$\nu \Phi_-(\nu) + \mathbf{M} \Phi_-(\nu) = \nu [\mathbf{W}_+ \Phi_+(\nu) + \mathbf{W}_- \Phi_-(\nu)]. \quad (60b)$$

At this point we find, after noting some basic properties of $\Psi(\xi)$, that we can write

$$\mathbf{W}_- = \mathbf{D} \mathbf{W}_+ \mathbf{D}, \quad (61)$$

where the $3N \times 3N$ diagonal matrix \mathbf{D} can be written as

$$\mathbf{D} = \text{diag}\{\mathbf{S}, \mathbf{S}, \dots, \mathbf{S}\} \quad (62)$$

with \mathbf{S} as given by Eq. (45). We now multiply Eq. (60b) by \mathbf{D} and rewrite Eqs. (60) as

$$\nu \Phi_+(\nu) - \mathbf{M} \Phi_+(\nu) = \nu [\mathbf{W}_+ \Phi_+(\nu) + \mathbf{D} \mathbf{W}_+ \mathbf{D} \Phi_-(\nu)] \quad (63a)$$

and

$$\nu \mathbf{D} \Phi_-(\nu) + \mathbf{M} \mathbf{D} \Phi_-(\nu) = \nu [\mathbf{D} \mathbf{W}_+ \Phi_+(\nu) + \mathbf{W}_+ \mathbf{D} \Phi_-(\nu)]. \quad (63b)$$

Now let

$$\mathbf{U} = \Phi_+(\nu) + \mathbf{D} \Phi_-(\nu) \quad (64a)$$

and

$$\mathbf{V} = \Phi_+(\nu) - \mathbf{D} \Phi_-(\nu) \quad (64b)$$

and add Eqs. (63) to obtain

$$\nu[\mathbf{I} - (\mathbf{I} + \mathbf{D})\mathbf{W}_+] \mathbf{U} = \mathbf{M}\mathbf{V}, \tag{65}$$

where now \mathbf{I} is the $3N \times 3N$ identity matrix. We also compute the difference between Eqs. (63) to find

$$\nu[\mathbf{I} - (\mathbf{I} - \mathbf{D})\mathbf{W}_+] \mathbf{V} = \mathbf{M}\mathbf{U}. \tag{66}$$

We now can eliminate $\mathbf{V}(\nu)$ between Eqs. (65) and (66) to find the eigenvalue problem

$$\mathbf{A}\mathbf{U} = \lambda\mathbf{U}, \tag{67}$$

where $\lambda = 1/\nu^2$ and

$$\mathbf{A} = \mathbf{M}^{-1}[\mathbf{I} - (\mathbf{I} - \mathbf{D})\mathbf{W}_+] \mathbf{M}^{-1}[\mathbf{I} - (\mathbf{I} + \mathbf{D})\mathbf{W}_+]. \tag{68}$$

And so our first computational job is to find the $3N$ eigenvalues of \mathbf{A} . However we first wish to address the issue of infinite values of the separation constant ν (or equivalently, the eigenvalues of \mathbf{A} that approach zero as N tends to infinity). We first introduce

$$\Lambda(z) = \mathbf{I} + z \int_{-\gamma}^{\gamma} \Psi(\xi) \frac{d\xi}{\xi - z} \tag{69a}$$

and note that we consider $\Lambda(z)$ to be the exact version of the discrete-ordinates quantity

$$\Omega(z) = \mathbf{I} + z \sum_{k=1}^N w_k \left[\Psi(\xi_k) \frac{1}{\xi_k - z} - \Psi(-\xi_k) \frac{1}{\xi_k + z} \right]. \tag{69b}$$

Since we know that the separation constants ν_j defined by the zeros of $\det \Omega(z)$ are the same as those we compute from the eigenvalues of the matrix \mathbf{A} , we base our discussion about the eigenvalues of \mathbf{A} (that accumulate at zero as N tends to infinity) on the zeros of $\det \Lambda(z)$ as z tends to infinity. We find that

$$\det \Lambda(z) \sim \frac{M}{z^4}, \quad M \neq 0, \tag{70}$$

as $z \rightarrow \infty$, and so we conclude that, as N tends to infinity, \mathbf{A} should have $\lambda=0$ as a (two-fold) repeated eigenvalue. And so instead of using Eq. (54) for the two smallest eigenvalues of \mathbf{A} we use instead the following four exact solutions of Eq. (43):

$$\mathbf{G}_1 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \tag{71a}$$

and

$$\mathbf{G}_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \tag{71b}$$

along with

$$\mathbf{G}_3 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \tag{71c}$$

and

$$\mathbf{G}_4(\tau, \xi) = (\tau - \xi) \begin{bmatrix} \omega - 5/2 \\ 0 \\ 1 \end{bmatrix}. \tag{71d}$$

If we now let

$$\mathbf{G}_{\pm}(\tau) = [\mathbf{G}^T(\tau, \pm \xi_1) \quad \mathbf{G}^T(\tau, \pm \xi_2) \quad \cdots \quad \mathbf{G}^T(\tau, \pm \xi_N)]^T, \tag{72}$$

then our discrete-ordinates solution can be written (after we exclude all solutions that are not bounded as τ tends to infinity) as

$$\mathbf{G}_{\pm}(\tau) = A_1 \Phi_1 + A_2 \Phi_2 + B_1 \Phi_3 + \sum_{j=3}^{3N} A_j \Phi_{\pm}(\nu_j) e^{-\tau/\nu_j}, \tag{73}$$

where B_1 and A_j , for $j=1,2,\dots,3N$, are arbitrary constants. In addition

$$\Phi_j = [\mathbf{G}_j^T \quad \mathbf{G}_j^T \quad \cdots \quad \mathbf{G}_j^T]^T, \quad j=1,2,3, \tag{74}$$

and the $\Phi_{\pm}(\nu_j)$ are available from Eqs. (64), (65), and (66). We find

$$\Phi_+(\nu_j) = \frac{1}{2}[\mathbf{I} + \nu_j \mathbf{M}^{-1}[\mathbf{I} - (\mathbf{I} + \mathbf{D})\mathbf{W}_+]] \mathbf{U}_j \tag{75}$$

and

$$\Phi_-(\nu_j) = \frac{1}{2}[\mathbf{I} - \nu_j \mathbf{M}^{-1}[\mathbf{I} - (\mathbf{I} + \mathbf{D})\mathbf{W}_+]] \mathbf{U}_j, \tag{76}$$

where \mathbf{U}_j is the eigenvector of \mathbf{A} that corresponds to the eigenvalue λ_j . Looking back now to Eq. (44), we find, for this formulation, that the boundary condition can be written as

$$\mathbf{G}_+(0) - (1 - \alpha) \mathbf{R}_s \mathbf{G}_-(0) - 2\alpha \mathbf{R}_d \mathbf{G}_-(0) = \mathbf{R}, \tag{77}$$

where the known right-hand side is given by

$$\mathbf{R} = [\mathbf{R}^T(\xi_1) \quad \mathbf{R}^T(\xi_2) \quad \cdots \quad \mathbf{R}^T(\xi_N)]^T. \tag{78}$$

Note that $\mathbf{R}(\xi)$ is given by Eq. (47). In addition, we find we can write the specular matrix as

$$\mathbf{R}_s = \text{diag}\{\mathbf{S}, \mathbf{S}, \dots, \mathbf{S}\}, \tag{79}$$

where \mathbf{S} is given by Eq. (45). Finally, to account for diffuse reflection, \mathbf{R}_d is a $3N \times 3N$ matrix each $3 \times 3N$ row of which is given by

$$\mathbf{R}_r = [w_1 \xi_1 \mathbf{Y}(\xi_1) \quad \omega_2 \xi_2 \mathbf{Y}(\xi_2) \quad \cdots \quad \omega_N \xi_N \mathbf{Y}(\xi_N)], \tag{80}$$

where $\mathbf{Y}(\xi)$ is given by Eq. (46). It is clear that Eq. (77) is a general result, but when the exact terms Φ_1 , Φ_2 , and Φ_3 are used in Eq. (44) the integrals resulting from the diffuse reflection can be done exactly. Finally, we note that since Φ_3 satisfies the homogeneous version of Eq. (77) the constant B_1 cannot be determined from that equation. However, we can impose on our solution the additional (arbitrary) normalization condition

$$\lim_{\tau \rightarrow \infty} [N_*(\tau) + T_*(\tau)] = \Gamma_*. \tag{81}$$

At this point, we follow other works^{15,18,19} and use $\Gamma_* = 0$ which, when we consider Eqs. (48), (49), and (73), yields

$$B_1 = (\omega - 5/2)A_1. \tag{82}$$

Considering now the quantities we wish to evaluate, we substitute Eq. (73) into Eqs. (48) and (49) to find, after using Eq. (82),

$$N_*(\tau) = (K/\sigma) \left\{ -\tau - A_1 + \frac{1}{\pi^{1/2}} \sum_{j=3}^{3N} A_j [\mathbf{N}_+ \Phi_+(\nu_j) + \mathbf{N}_- \Phi_-(\nu_j)] e^{-\tau/\nu_j} \right\} \quad (83)$$

and

$$T_*(\tau) = (K/\sigma) \left\{ \tau + A_1 + \frac{2}{3\pi^{1/2}} \sum_{j=3}^{3N} A_j [\mathbf{T}_+ \Phi_+(\nu_j) + \mathbf{T}_- \Phi_-(\nu_j)] e^{-\tau/\nu_j} \right\}, \quad (84)$$

where

$$\mathbf{N}_\pm = [w_1 \mathbf{N}(\pm \xi_1) \quad w_2 \mathbf{N}(\pm \xi_2) \quad \cdots \quad w_N \mathbf{N}(\pm \xi_N)] \quad (85a)$$

and

$$\mathbf{T}_\pm = [w_1 \mathbf{T}(\pm \xi_1) \quad w_2 \mathbf{T}(\pm \xi_2) \quad \cdots \quad w_N \mathbf{T}(\pm \xi_N)] \quad (85b)$$

with

$$\mathbf{N}(\xi) = [n_1(\xi) \quad n_2(\xi) \quad n_3(\xi)] \quad (86a)$$

and

$$\mathbf{T}(\xi) = [t_1(\xi) \quad t_2(\xi) \quad t_3(\xi)]. \quad (86b)$$

Note that the components of the vectors introduced in Eqs. (86) are defined by Eqs. (50) and (51). We note also that in obtaining Eqs. (83) and (84) from Eqs. (48) and (49), we have analytically integrated the first three terms of Eq. (73), but we have used our defined quadrature scheme to integrate the remaining terms. Now putting Eqs. (83) and (84) back in terms of the x variable, we find

$$N(x) = -x - A_1/\sigma + \frac{1}{\sigma\pi^{1/2}} \sum_{j=3}^{3N} A_j [\mathbf{N}_+ \Phi_+(\nu_j) + \mathbf{N}_- \Phi_-(\nu_j)] e^{-\sigma x/\nu_j} \quad (87)$$

and

$$T(x) = x + A_1/\sigma + \frac{2}{3\sigma\pi^{1/2}} \sum_{j=3}^{3N} A_j [\mathbf{T}_+ \Phi_+(\nu_j) + \mathbf{T}_- \Phi_-(\nu_j)] e^{-\sigma x/\nu_j}, \quad (88)$$

where we have imposed the normalization $K=1$. If now we let

$$T_{\text{asy}}(x) = x + A_1/\sigma \quad (89)$$

and define the temperature-jump coefficient ζ by

$$T_{\text{asy}}(0) = \zeta \frac{d}{dx} T_{\text{asy}}(x)|_{x=0}, \quad (90)$$

then clearly

$$\zeta = A_1/\sigma. \quad (91)$$

To be very clear, we note that the constant Γ_* introduced in Eq. (81) does not affect the temperature-jump coefficient or the temperature perturbation $T(x)$. In fact, another choice of Γ_* would change only the density perturbations $N(x)$ by the addition of a constant factor.

V. SPECIAL CASES

Having developed our general solution to the temperature-jump problem for the CLF model of the linearized Boltzmann equation, we are ready to list the specific forms of certain basic quantities for the three special cases we consider in this work.

A. Constant collision frequency

For this case, the classical BGK model, we write

$$\eta(c) = 1, \quad (92)$$

and so we find

$$\gamma = \infty, \quad (93a)$$

$$\Gamma = 0, \quad (93b)$$

$$\omega = 3/2, \quad (93c)$$

$$\beta_0 = 4/\pi^{1/2}, \quad (93d)$$

and

$$\sigma = 1. \quad (93e)$$

In addition, we find from Eqs. (39)

$$\Psi(\xi) = \frac{e^{-\xi^2}}{\pi^{1/2}} \begin{bmatrix} 1 & \xi & \xi^2 - 1/2 \\ 2\xi & 2\xi^2 & 2\xi(\xi^2 - 1/2) \\ (2/3)(\xi^2 - 1/2) & (2/3)\xi(\xi^2 - 1/2) & (2/3)(\xi^4 - \xi^2 + 5/4) \end{bmatrix}. \tag{94}$$

We can also use Eqs. (50) and (51) to write Eqs. (86), for this case, as

$$\mathbf{N}(\xi) = e^{-\xi^2} [1 \quad \xi \quad \xi^2 - 1/2] \tag{95a}$$

and

$$\mathbf{T}(\xi) = e^{-\xi^2} [\xi^2 - 1/2 \quad \xi(\xi^2 - 1/2) \quad \xi^4 - \xi^2 + 5/4]. \tag{95b}$$

B. The Williams model

For this case we write

$$\eta(c) = c, \tag{96}$$

and so we find

$$\gamma = 1, \tag{97a}$$

$$\Gamma = -1/4, \tag{97b}$$

$$\omega = 2, \tag{97c}$$

$$\beta_0 = 2, \tag{97d}$$

and

$$\sigma = (6/5)\pi^{-1/2}. \tag{97e}$$

In addition, we find from Eqs. (39)

$$\Psi(\xi) = \frac{1}{2} \begin{bmatrix} 1 & (3/4)\pi^{1/2}\xi & 0 \\ (9/8)\pi^{1/2}\xi & 3\xi^2 & (9/16)\pi^{1/2}\xi \\ 0 & (3/16)\pi^{1/2}\xi & 1 \end{bmatrix}. \tag{98}$$

Again we can use Eqs. (50) and (51) to write Eqs. (86), for this case, as

$$\mathbf{N}(\xi) = [(1/2)\pi^{1/2} \quad \xi \quad -(1/4)\pi^{1/2}] \tag{99a}$$

and

$$\mathbf{T}(\xi) = [0 \quad \xi/2 \quad (3/4)\pi^{1/2}]. \tag{99b}$$

C. The rigid-sphere model

For the rigid-sphere model, we follow Loyalka and Hickey¹¹ and write

$$\eta(c) = \left(2c + \frac{1}{c}\right) \frac{\pi^{1/2}}{2} \operatorname{erf}(c) + e^{-c^2}, \tag{100}$$

where $\operatorname{erf}(c)$ is the error function. Here we find the exact results

$$\gamma = 1/\pi^{1/2} \tag{101a}$$

and

$$\omega = 7/4, \tag{101b}$$

and we have used the software package MAPLE V to find the numerical values

$$\beta_0 = 0.7978845608029, \tag{101c}$$

$$\Gamma = -0.06063367084623, \tag{101d}$$

and

$$\sigma = 0.2753345876233. \tag{101e}$$

In regard to Eqs. (39), (50), and (51), we have used numerical methods to evaluate the various functions required to establish $\Psi(\xi)$, $\mathbf{N}(\xi)$, and $\mathbf{T}(\xi)$. As discussed in a previous work¹² concerning Kramers' problem, we let

$$f(c) = \frac{c}{\eta(c)} \tag{102}$$

and note that we can show, for the considered case, that $f'(c) > 0$, for $c \geq 0$ and so the inverse function

$$m(\xi) = f^{-1}(|\xi|), \quad \xi \in [-\gamma, \gamma], \tag{103}$$

exists, and thus we can write the required functions (written symbolically as)

$$P(\xi) = \int_{M_\xi} p(c) dc \tag{104}$$

as

$$P(\xi) = \int_{m(\xi)}^\infty p(c) dc, \tag{105}$$

which can be evaluated numerically once $m(\xi)$ is available; as before¹² we use Newton's method to establish the required numerical values of $m(\xi)$.

VI. NUMERICAL RESULTS

The first thing we must do is to define the quadrature scheme to be used in our discrete-ordinates solution, and, since we have considered three different cases, to which we refer as case 1, case 2, and case 3 while meaning, respectively, the BGK model, the Williams model, and the rigid-sphere model, we have used three different maps. For case 1, we used the (nonlinear) transformation

$$u(\xi) = \exp\{-\xi\} \tag{106}$$

to map $\xi \in [0, \infty)$ into $u \in [0, 1]$, and we then used the Gauss-Legendre scheme mapped (linearly) onto the interval $[0, 1]$. For cases 2 and 3 we simply mapped the Gauss-Legendre scheme onto, respectively, the intervals $[0, 1]$ and $[0, \pi^{-1/2}]$. Having defined our quadrature scheme, we used the driver program RG from the EISPACK collection²⁰ to find the eigenvalues and eigenvectors defined by Eq. (67). And so, after using the subroutines DGECO and DGENL from the LINPACK package²¹ to solve the linear system derived from Eq. (77) to

TABLE I. The temperature-jump coefficient ζ .

Model	$\alpha=0.1$	$\alpha=0.3$	$\alpha=0.5$	$\alpha=0.6$	$\alpha=0.7$	$\alpha=0.9$	$\alpha=1.0$
Case 1	21.45012	6.630514	3.629125	2.867615	2.317534	1.570264	1.302716
Case 2	21.19359	6.406417	3.435960	2.689383	2.153897	1.434848	1.180947
Case 3	21.24657	6.452894	3.476180	2.726563	2.188095	1.463247	1.206526

find the constants A_j , for $j=1,2,\dots,3N$, we consider our solution complete. Finally, but importantly, we have found, that some elements of the matrix-valued function $\Psi(\xi)$ as defined by Eqs. (39) can be essentially zero (from a computational point-of-view). In such cases, we found that by defining an element to be precisely zero when that element is less than, say, $\epsilon=10^{-50}$, we greatly increased the ability of the linear-algebra package to yield the required number of independent eigenvectors when there is a (nearly) repeated eigenvalue.

To complete our work we list in Tables I and II some results obtained from our FORTRAN implementation of the developed solution of the temperature-jump problem for the three explicitly considered cases. We note that our results are given with what we believe to be seven, in Table I, and six, in Table II, figures of accuracy. While we have no proof of the accuracy achieved in this work, we have done some things to support the confidence we have. First of all our results for case 1 agree perfectly with some (quasi) independent calculations¹⁵ done previously. In addition we found agreement, to three figures, with the value of ζ for case 2, with $\alpha=1.0$, that was reported by Cassell and Williams.²² We also found apparent convergence in our numerical results as we increased N , the number of quadrature points used, and to reduce the possibility of FORTRAN errors, we have implemented two independent versions of the algorithm. Finally, we note that for case 2, the Williams model, the three-vector \mathbf{G} problem can, as discussed by Williams and Cassell,²² be

solved as three consecutive scalar problems. This approach has been used by Bartz²³ to confirm all of the results given in Tables I and II that refer to case 2.

We have typically used $N=50$ to generate results for the temperature-jump coefficient ζ and the temperature and density perturbations good to, say, five or six significant figures, and so we note that our FORTRAN implementation (no special effort was made to make the code especially efficient) of our discrete-ordinates solution (with $N=50$) runs in a few seconds on a 400 MHz Pentium-based PC.

To have some idea of the merits of the CLF model, as we have used it here, we note that Loyalka⁹ and Sone, Ohwada, and Aoki¹⁰ give, respectively, for the case $\alpha=1$, the results $\zeta=1.2486$ and $\zeta=1.2482$ for the case of the linearized Boltzmann equation relevant to hard-sphere collisions. If we consider these results to be the best available for the problem as defined in this work, then our use of the CLF model for the rigid-sphere case ($\zeta=1.206526$) provides a modest improvement (in regard to the temperature-jump coefficient for the case $\alpha=1$) over the classical BGK model ($\zeta=1.302716$).

VII. FINAL COMMENTS

In concluding this work, we note that we have been able to extend the use of our analytical version of the discrete-ordinates method to solve the temperature-jump problem for a general version of the variable collision frequency model.

TABLE II. The temperature and density perturbations for the case $\alpha=0.5$.

x	Case 1		Case 2		Case 3	
	$T(x)$	$N(x)$	$T(x)$	$N(x)$	$T(x)$	$N(x)$
0.0	2.91597	-3.07437	3.10167	-3.27399	3.00508	-3.16704
0.1	3.18042	-3.31664	3.30560	-3.42542	3.23434	-3.35822
0.2	3.36278	-3.48323	3.45447	-3.54940	3.39748	-3.50093
0.3	3.52167	-3.62947	3.58758	-3.66556	3.54146	-3.63010
0.4	3.66754	-3.76478	3.71209	-3.77746	3.67483	-3.75193
0.5	3.80489	-3.89310	3.83110	-3.88665	3.80132	-3.86906
0.6	3.93615	-4.01653	3.94628	-3.99397	3.92295	-3.98291
0.7	4.06283	-4.13633	4.05866	-4.09990	4.04097	-4.09435
0.8	4.18593	-4.25334	4.16891	-4.20480	4.15620	-4.20394
0.9	4.30614	-4.36814	4.27749	-4.30888	4.26921	-4.31208
1.0	4.42400	-4.48113	4.38475	-4.41233	4.38044	-4.41906
2.0	5.52928	-5.55674	5.42014	-5.42888	5.44006	-5.45530
3.0	6.57466	-6.58912	6.43030	-6.43349	6.46062	-6.46735
4.0	7.59758	-7.60560	7.43378	-7.43503	7.46901	-7.47216
5.0	8.61013	-8.61476	8.43508	-8.43559	8.47273	-8.47426
6.0	9.61737	-9.62011	9.43559	-9.43581	9.47447	-9.47523
7.0	10.6217	-10.6234	10.4358	-10.4359	10.4753	-10.4757
8.0	11.6243	-11.6254	11.4359	-11.4359	11.4757	-11.4759
9.0	12.6260	-12.6267	12.4359	-12.4359	12.4759	-12.4761
10.0	13.6271	-13.6275	13.4359	-13.4360	13.4761	-13.4761
20.0	23.6291	-23.6291	23.4360	-23.4360	23.4762	-23.4762

In addition to a formulation valid for a general form of the collision frequency, the algorithm was implemented to yield high-quality numerical results for three well-regarded forms. Since the reported solution is easy to evaluate and yields excellent numerical results, and since the developed code runs typically in a few seconds on a 400 MHz Pentium-based PC, we consider the solution ready for additional applications. It is clear that the formalism reported here can readily be used to solve other classical problems, in semi-infinite media and for plane-parallel channel flow, in rarefied-gas dynamics, when one of the three explicitly developed variants of the CLF model equation is required to give (perhaps) more realistic results than the standard BGK model can provide. And finally, since the development reported here is also general, we believe that our solution can immediately be used with forms of the collision frequency additional to the three special cases considered.

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