

FURTHER RESULTS CONCERNING EXACT ANALYTICAL SOLUTIONS BASIC TO TWO-BODY ORBITS

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Abstract. Complex-variable techniques are used to establish exact analytical solutions to a class of two-body problems. In view of Lambert's theorem, two points on the conic, the chord-distance between the two points, and the time interval are considered given, and subsequently the solutions for the semi-major axis required to define the orbit are developed and expressed ultimately in terms of elementary quadratures.

1. Introduction

In a recent paper (Burniston and Siewert, 1973a) hereafter referred to as I, we applied a technique (Burniston and Siewert, 1973b) which makes use of Riemann problems in the theory of analytic functions to the problem of determining the semi-major axis of an orbit, given two points on the orbit, the chord-distance between the two points and the time interval. Specifically, with reference to Figure 1, we note (Wintner, 1947) that the points P_1 and P_2 are located at distances r_1 and r_2 respectively from the attracting focus S and c is the chord-distance. It is well known that the problem is not well posed unless the shaded region A in Figure 1 is known to contain or not to contain the attracting focus S . If the orbit is an ellipse we also need to know whether or not A contains the empty focus S^* . In I we presented solutions for the cases: (i) hyperbolic or parabolic orbits with $S \notin A$, (ii) elliptic orbits with $S \notin A$ and $S^* \notin A$ and (iii) elliptic orbits with both $S \in A$ and $S^* \in A$. For elliptic orbits, we also allowed the body to have made k specified revolutions in addition to the arc P_1P_2 , with the condition that either

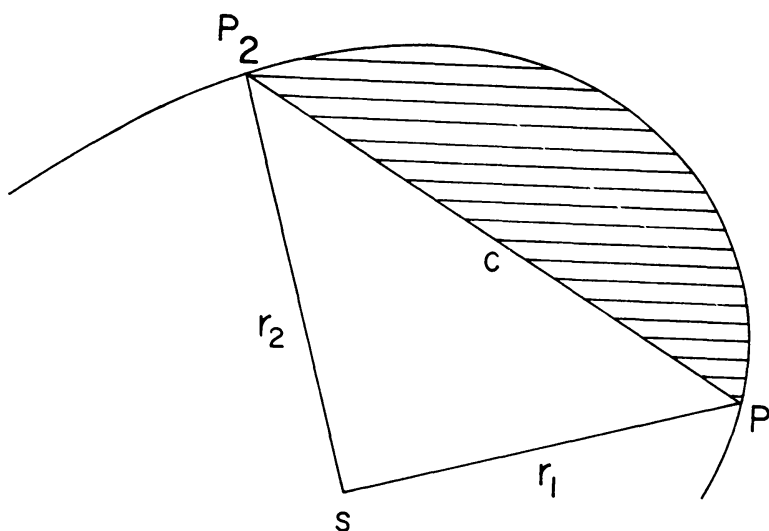


Fig. 1. The reference configuration.

$S \notin A$ and $S^* \notin A$ or $S \in A$ and $S^* \in A$. We now wish to report solutions for the remaining cases: (i) hyperbolic or parabolic orbits with $S \in A$, (ii) elliptic orbits with $S \in A$ and $S^* \notin A$ and (iii) elliptic orbits with $S \notin A$ and $S^* \in A$. We shall also include the possibility that the body has made k revolutions in addition to the arc P_1P_2 , with either $S \in A$ and $S^* \notin A$ or $S \notin A$ and $S^* \in A$.

2. Preliminary Analysis

We first consider the hyperbolic and parabolic cases such that $S \in A$ and those elliptic orbits with $S \in A$ and $S^* \notin A$. As discussed by Wintner (1947), the problem here can be defined by assigning an appropriate path of integration to

$$M = \oint_{\Gamma} \left[\frac{1}{x} + h \right]^{-1/2} dx, \quad (1)$$

$(r_1+r_2+c)/2$
 $(r_1+r_2-c)/2$

where r_1, r_2 and c are the distances so denoted in Figure 1, and

$$M = \sqrt{2}(t_2 - t_1) \quad (2)$$

is the time interval. We consider that M, r_1, r_2 and c are given and thus seek the energy constant h , or alternatively, the semi-major axis

$$a = -\frac{1}{2h}. \quad (3)$$

We find, on letting $h = -z$, that we can change the integration variable in Equation (1) to obtain

$$M = \left(\int_{\alpha}^{\infty} + \int_{\beta}^{\infty} \right) \frac{1}{\sqrt{t-z}} \frac{dt}{t^2}, \quad (4)$$

where

$$\alpha = 2(r_1 + r_2 + c)^{-1} \quad (5a)$$

and

$$\beta = 2(r_1 + r_2 - c)^{-1}. \quad (5b)$$

In addition, we note that the square-root function in Equation (4) is to be interpreted as the principal branch. It thus follows that the zeros, say z_i , of

$$\Omega(z) = M - \left(\int_{\alpha}^{\infty} + \int_{\beta}^{\infty} \right) \frac{1}{\sqrt{t-z}} \frac{dt}{t^2} \quad (6)$$

will yield, by way of $h = -z_i$ or Equation (3), the desired solution(s). Viewed as a function of a complex variable, we observe that $\Omega(z)$ is analytic in the plane cut from α to ∞ along the real axis.

We require the limiting values of $\Omega(z)$ as z approaches the cut $[\alpha, \infty)$ from above

(+) and below (-), and thus from Equation (6) we deduce that

$$\Omega^{\pm}(x) = M - \left(\int_x^{\beta} + 2 \int_{\beta}^{\infty} \right) \frac{1}{\sqrt{t-x}} \frac{dt}{t^2} \mp i \int_{\alpha}^x \frac{1}{\sqrt{x-t}} \frac{dt}{t^2}, \quad \alpha \leq x \leq \beta, \quad (7a)$$

and

$$\Omega^{\pm}(x) = M - 2 \int_x^{\infty} \frac{1}{\sqrt{t-x}} \frac{dt}{t^2} \mp i \left(\int_{\alpha}^{\beta} + 2 \int_{\beta}^x \right) \frac{1}{\sqrt{x-t}} \frac{dt}{t^2}, \quad x \geq \beta. \quad (7b)$$

The number of zeros of $\Omega(z)$ can now be computed by using the argument principle (Ahlfors, 1953) in a domain determined by the contour C given in Figure 2, with

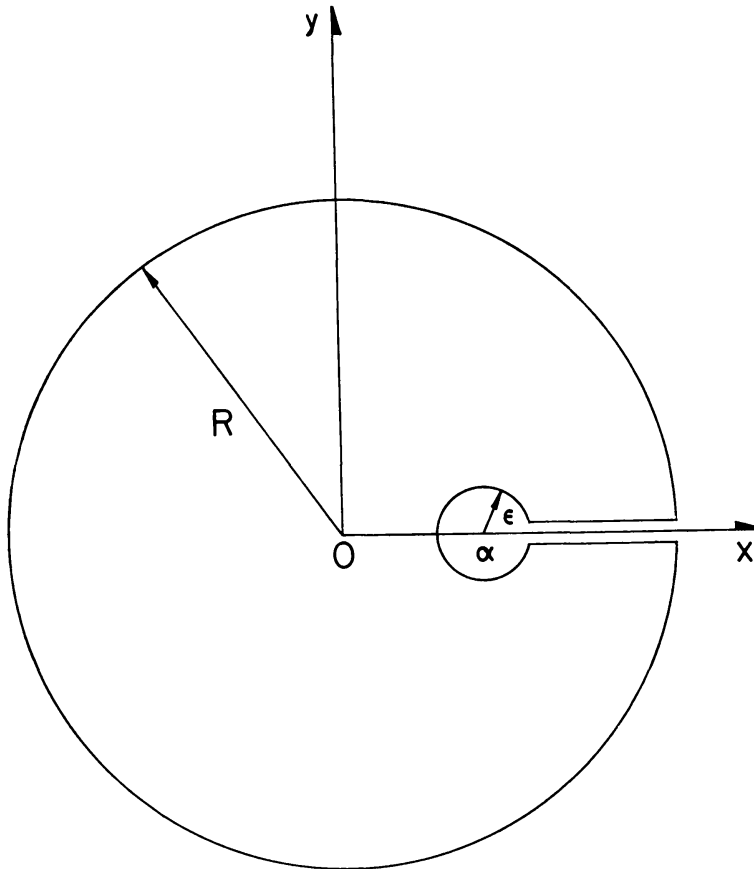


Fig. 2. The contour C .

$R \rightarrow \infty$ and $\varepsilon \rightarrow 0$. We find that if

$$M > \left(\int_{\alpha}^{\infty} + \int_{\beta}^{\infty} \right) \frac{1}{\sqrt{t-\alpha}} \frac{dt}{t^2}, \quad (8)$$

then $\Omega(z)$ has no zeros, whereas if

$$M < \left(\int_{\alpha}^{\infty} + \int_{\beta}^{\infty} \right) \frac{1}{\sqrt{t-\alpha}} \frac{dt}{t^2}, \quad (9)$$

then $\Omega(z)$ has precisely one real zero. This zero will be negative if $\Omega(0) < 0$, i.e. if

$$M < \frac{2}{3}(\alpha^{-3/2} + \beta^{-3/2}), \quad (10)$$

which is the hyperbolic time criterion. Consequently if

$$\frac{2}{3}(\alpha^{-3/2} + \beta^{-3/2}) < M < \frac{\pi}{\alpha\sqrt{\alpha}} - \frac{1}{\beta\sqrt{\alpha}} \left(\sqrt{\frac{\beta}{\alpha}} - 1 + \frac{\beta}{\alpha} \tan^{-1} \sqrt{\frac{\beta}{\alpha}} - 1 \right), \quad (11)$$

then the orbit is an ellipse.

If we now allow the possibility of the body having made k revolutions in addition to the arc P_1P_2 , still with $S \in A$ and $S^* \notin A$ then clearly we require the zeros of

$$\Omega_k(z) = M - \frac{k\pi}{z\sqrt{z}} - \left(\int_{\alpha}^{\infty} + \int_{\beta}^{\infty} \right) \frac{1}{\sqrt{t-z}} \frac{dt}{t^2}. \quad (12)$$

On taking the principal branch of \sqrt{z} , we note that $\Omega_k(z)$ is analytic in the plane cut from $-\infty$ to 0 and from α to ∞ , along the real axis. By employing the argument principle once more we deduce that $\Omega_k(z)$ has precisely one (real) zero if $\Omega_k(\alpha) > 0$, i.e. if

$$M > \frac{k\pi}{\alpha\sqrt{\alpha}} + \left(\int_{\alpha}^{\infty} + \int_{\beta}^{\infty} \right) \frac{1}{\sqrt{t-\alpha}} \frac{dt}{t^2}, \quad k = 1, 2, 3, \dots \quad (13)$$

If $\Omega_k(\alpha) \leq 0$, the function $\Omega_k(z)$ will have two zeros which will be complex if $|\Omega_k(\alpha)|$ is sufficiently large. We will consider this point in detail in the next section.

We now consider the case for elliptic orbits when $S \notin A$ but $S^* \in A$. Here we need to consider the function

$$\hat{\Omega}(z) = M - \frac{\pi}{z\sqrt{z}} + \left(\int_{\alpha}^{\infty} + \int_{\beta}^{\infty} \right) \frac{1}{\sqrt{t-z}} \frac{dt}{t^2}. \quad (14)$$

Again by the argument principle, we find that $\hat{\Omega}(z)$ has precisely one zero in the cut plane if $\hat{\Omega}(\alpha) > 0$, i.e. if

$$M > \frac{\pi}{\alpha\sqrt{\alpha}} - \left(\int_{\alpha}^{\infty} + \int_{\beta}^{\infty} \right) \frac{1}{\sqrt{t-\alpha}} \frac{dt}{t^2}. \quad (15)$$

If we allow k complete revolutions in addition to the arc P_1P_2 but still with $S \notin A$ and $S^* \in A$, then the appropriate function is

$$\hat{\Omega}_k(z) = M - \frac{(k+1)\pi}{z\sqrt{z}} + \left(\int_{\alpha}^{\infty} + \int_{\beta}^{\infty} \right) \frac{1}{\sqrt{t-z}} \frac{dt}{t^2}, \quad (16)$$

which can be shown to have exactly one zero in the cut plane if $\hat{\Omega}_k(\alpha) > 0$, i.e. if

$$M > \frac{(k+1)\pi}{\alpha\sqrt{\alpha}} - \left(\int_{\alpha}^{\infty} + \int_{\beta}^{\infty} \right) \frac{1}{\sqrt{t-\alpha}} \frac{dt}{t^2}. \quad (17)$$

We shall now derive analytical expressions for the zeros of $\Omega(z)$, $\hat{\Omega}(z)$, $\Omega_k(z)$ and $\hat{\Omega}_k(z)$ for $k=1, 2, \dots$. In so far as the analysis is concerned it is clear that we may combine the cases $\hat{\Omega}(z)$ and $\hat{\Omega}_k(z)$, $k=1, 2, 3, \dots$, into one case, namely $\hat{\Omega}_k(z)$, $k=0, 1, 2, \dots$.

3. Basic Analysis and Results

As was discussed in detail in I we now proceed to solve the transcendental equations of Section 2 by appealing to appropriately posed Riemann problems. We first consider Equation (6), assuming that inequality (9) holds. Clearly there exists an $F(z)$ which is analytic and non-zero in the cut plane such that

$$\Omega(z) = (z - z_0) F(z), \quad (18)$$

where z_0 is the required zero of $\Omega(z)$. If we take limiting values on the cut, we may write

$$F^+(x) = G(x) F^-(x), \quad \alpha < x < \infty, \quad (19)$$

where

$$G(x) = \frac{\Omega^+(x)}{\Omega^-(x)}. \quad (20)$$

On using the terminology of Muskhelishvili (1953), we can say that $F(z)$ is a canonical solution of the Riemann problem defined by Equation (19). In fact we can write

$$F(z) = \frac{M}{z - \alpha} \exp \left[\frac{1}{\pi} \int_{\alpha}^{\infty} \arg \Omega^+(t) \frac{dt}{t - z} \right], \quad (21)$$

and so from Equation (18) we have the identity

$$z_0 = z - \frac{\Omega(z)(z - \alpha)}{M} \exp \left[-\frac{1}{\pi} \int_{\alpha}^{\infty} \arg \Omega^+(t) \frac{dt}{t - z} \right], \quad (22)$$

where the argument function has been chosen so that $\arg \Omega^+(\alpha) = -\pi$. Thus from Equation (3) we can now write

$$a = \frac{1}{2} M \left(Mz - \Omega(z)(z - \alpha) \exp \left[-\frac{1}{\pi} \int_{\alpha}^{\infty} \arg \Omega^+(t) \frac{dt}{t - z} \right] \right)^{-1}, \quad (23)$$

$S \in A$, or $S \in A$ and $S^* \notin A$.

Although the choice of z in Equation (23) can alter the computational merit of that

expression, an especially simple result is achieved by setting $z=0$:

$$a = \frac{M}{2\alpha} [M - \frac{2}{3}(\alpha^{-3/2} + \beta^{-3/2})]^{-1} \exp \left[\frac{1}{\pi} \int_{\alpha}^{\infty} \arg \Omega^+(t) \frac{dt}{t} \right],$$

$$S \in A, \text{ or } S \in A \text{ and } S^* \notin A. \quad (24)$$

For computational purposes it is probably more expedient to make the change of variable $\tau=1/t$ so that we can write Equation (24) in the form

$$a = \frac{M}{2\alpha} [M - \frac{2}{3}(\alpha^{-3/2} + \beta^{-3/2})]^{-1} \exp \left[-\frac{1}{\pi} \int_0^{1/\beta} \tan^{-1} \left(\frac{2I_1(\tau) - I_3(\tau)}{M - \pi\tau^{3/2}} \right) \frac{d\tau}{\tau} + \right.$$

$$\left. -\frac{1}{\pi} \int_{1/\beta}^{1/\alpha} \tan^{-1} \left\{ \frac{I_1(\tau)}{M - \pi\tau^{3/2} + I_2(\tau)} \right\} \frac{d\tau}{\tau} \right], \quad S \in A, \text{ or } S \in A \text{ and } S^* \notin A, \quad (25)$$

where the functions $I_1(\tau)$, $I_2(\tau)$ and $I_3(\tau)$ are as in I, namely

$$I_1(\tau) = \tau^{3/2} \left[\frac{\sqrt{1-\alpha\tau}}{\alpha\tau} + \frac{1}{2} \ln \left(\frac{1+\sqrt{1-\alpha\tau}}{1-\sqrt{1-\alpha\tau}} \right) \right], \quad (26a)$$

$$I_2(\tau) = \tau^{3/2} \left[\frac{\sqrt{\beta\tau-1}}{\beta\tau} + \tan^{-1} \sqrt{\beta\tau-1} \right], \quad (26b)$$

and

$$I_3(\tau) = I_1(\tau) - \tau^{3/2} \left[\frac{\sqrt{1-\beta\tau}}{\beta\tau} + \frac{1}{2} \ln \left(\frac{1+\sqrt{1-\beta\tau}}{1-\sqrt{1-\beta\tau}} \right) \right]. \quad (26c)$$

We now consider the case of elliptic motion, where we allow the body to make k complete revolutions in addition to the arc P_1P_2 , but still with $S \in A$ and $S^* \notin A$, and, of course, when inequality (13) is satisfied. We now can write

$$z\Omega_k(z) = (z - z_k) F_k(z), \quad k = 1, 2, 3, \dots, \quad (27)$$

where $F_k(z)$ is the suitably normalized canonical solution of

$$F_k^+(x) = G_k(x) F_k^-(x), \quad x \in (-\infty, 0) \cup (\alpha, \infty), \quad (28)$$

where

$$G_k(x) = \frac{\Omega_k^+(x)}{\Omega_k^-(x)}. \quad (29)$$

With $\arg \Omega_k^+(\pm\infty)=0$, we can write this solution as

$$F_k(z) = M \exp \left[\frac{1}{\pi} \left(\int_{-\infty}^0 + \int_{\alpha}^{\infty} \right) \arg \Omega_k^+(t) \frac{dt}{t-z} \right], \quad (30)$$

and so, from Equation (27) we have the identities

$$z_k = \left[z \left(1 - \frac{\Omega_k(z)}{F_k(z)} \right) \right], \quad S \in A \text{ and } S^* \notin A, \quad (31)$$

and

$$a_k = \frac{1}{2z} \left[1 - \frac{\Omega_k(z)}{F_k(z)} \right]^{-1}, \quad S \in A \text{ and } S^* \notin A. \quad (32)$$

On letting $z = \alpha$, we have the concise result

$$a_k = \frac{1}{2\alpha} \left[1 - \frac{\Omega_k(\alpha)}{F_k(\alpha)} \right]^{-1}, \quad S \in A \text{ and } S^* \notin A, \quad (33)$$

where, after making appropriate variable changes,

$$\begin{aligned} F_k(\alpha) = M \exp & \left[-\frac{1}{\pi} \int_{-1/\alpha}^0 \tan^{-1} \left\{ \frac{k\pi |\tau|^{3/2}}{(1 - \alpha |\tau|)^{3/2} [M - I_5(\tau)]} \right\} \frac{d\tau}{\tau} + \right. \\ & - \frac{1}{\pi} \int_0^{1/\beta} \tan^{-1} \left\{ \frac{2I_1(\tau) - I_3(\tau)}{M - (k+1)\pi\tau^{3/2}} \right\} \frac{d\tau}{\tau(1 - \alpha\tau)} + \\ & \left. - \frac{1}{\pi} \int_{1/\beta}^{1/\alpha} \tan^{-1} \left\{ \frac{I_1(\tau)}{M - (k+1)\pi\tau^{3/2} + I_2(\tau)} \right\} \frac{d\tau}{\tau(1 - \alpha\tau)} \right], \quad (34) \end{aligned}$$

and

$$\Omega_k(\alpha) = M - \alpha^{-3/2} \left[(k+1)\pi - \frac{\alpha}{\beta} \sqrt{\frac{\beta}{\alpha} - 1} - \tan^{-1} \sqrt{\frac{\beta}{\alpha} - 1} \right], \quad (35)$$

where $I_1(\tau)$, $I_2(\tau)$ and $I_3(\tau)$ are given by Equations (26), and

$$\begin{aligned} I_5(\tau) = & \frac{|\tau|^{1/2}}{\alpha(1 - \alpha|\tau|)} \left[1 + \frac{\alpha}{\beta} \sqrt{1 + (\beta - \alpha)|\tau|} \right] + \\ & + \frac{|\tau|^{3/2}}{2(1 - \alpha|\tau|)^{3/2}} \left[\ln \left(\frac{1 - \sqrt{1 - \alpha|\tau|}}{1 + \sqrt{1 - \alpha|\tau|}} \right) + \right. \\ & \left. + \ln \left(\frac{\sqrt{1 + (\beta - \alpha)|\tau|} - \sqrt{1 - \alpha|\tau|}}{\sqrt{1 + (\beta - \alpha)|\tau|} + \sqrt{1 - \alpha|\tau|}} \right) \right]. \quad (36) \end{aligned}$$

An essentially similar analysis may be used to derive the desired solutions for $S \notin A$ and $S^* \in A$; thus we simply list

$$\hat{a}_k = \frac{1}{2\alpha} \left[1 - \frac{\hat{\Omega}_k(\alpha)}{\hat{F}_k(\alpha)} \right]^{-1}, \quad S \notin A \text{ and } S^* \in A, \quad k = 0, 1, 2, \dots, \quad (37)$$

where

$$\hat{\Omega}_k(\alpha) = M - \alpha^{-3/2} \left[k\pi + \frac{\alpha}{\beta} \sqrt{\frac{\beta}{\alpha} - 1} + \tan^{-1} \sqrt{\frac{\beta}{\alpha} - 1} \right], \quad k = 0, 1, 2, \dots, \quad (38)$$

and

$$\begin{aligned} \hat{F}_k(\alpha) = M \exp & \left[-\frac{1}{\pi} \int_{-1/\alpha}^0 \tan^{-1} \left\{ \frac{(k+1)\pi|\tau|^{3/2}}{(1-\alpha|\tau|)^{3/2} [M + I_5(\tau)]} \right\} \frac{d\tau}{\tau} + \right. \\ & -\frac{1}{\pi} \int_0^{1/\beta} \tan^{-1} \left\{ \frac{I_3(\tau) - 2I_1(\tau)}{M - k\pi\tau^{3/2}} \right\} \frac{d\tau}{\tau(1-\alpha\tau)} + \\ & \left. -\frac{1}{\pi} \int_{1/\beta}^{1/\alpha} \tan^{-1} \left\{ \frac{-I_1(\tau)}{M - k\pi\tau^{3/2} - I_2(\tau)} \right\} \frac{d\tau}{\tau(1-\alpha\tau)} \right]. \quad (39) \end{aligned}$$

We recall that inequality (15) has to be satisfied in order for the solution given by Equation (37) to be valid.

We now turn our attention to the multivalued case for $\Omega_k(z)$, $S \in A$ and $S^* \notin A$, $k \geq 1$. As was discussed previously if $\Omega_k(\alpha) < 0$, it follows that $\Omega_k(z)$ has two zeros in the cut plane say z_{k0} and z_{k1} , so that we may write

$$z(z - \alpha) \Omega_k(z) = (z - z_{k0})(z - z_{k1}) F_k(z), \quad (40)$$

where $F_k(z)$ is given by Equation (30). Thus on setting

$$K_k(z) = z(z - \alpha) \Omega_k(z) F_k^{-1}(z), \quad (41)$$

we have

$$z_{k0} = -B(v, \eta) - \sqrt{B^2(v, \eta) - C(v, \eta)}, \quad (42a)$$

and

$$z_{k1} = -B(v, \eta) + \sqrt{B^2(v, \eta) - C(v, \eta)}, \quad (42b)$$

where

$$B(v, \eta) = \frac{1}{2} \left[\frac{K_k(v) - K_k(\eta) - v^2 + \eta^2}{v - \eta} \right], \quad (43a)$$

and

$$C(v, \eta) = \frac{vK_k(\eta) - \eta K_k(v) + v\eta(v - \eta)}{v - \eta}, \quad (43b)$$

with v and η being two distinct points off the cut. A convenient choice is for v and η to be real numbers selected from the interval $(0, \alpha)$. Consequently z_{k0} and z_{k1} will lead, through use of Equation (3), to appropriate semi-major axes a_{k0} and a_{k1} say, provided z_{k0} and z_{k1} are real. Clearly the limiting case will be when the two zeros coincide at x_k say. As this will be a double zero of $\Omega_k(z)$ it may be determined in terms of k , α and β by considering the zeros of $\Omega'_k(z)$. From Equation (12) we may write, after some elementary algebra,

$$\Omega'_k(z) = \frac{3k\pi}{2z^{5/2}} - \frac{1}{\alpha z \sqrt{\alpha - z}} - \frac{1}{\beta z \sqrt{\beta - z}} + \frac{3}{2z} \left(\int_{\alpha}^{\infty} + \int_{\beta}^{\infty} \right) \frac{1}{\sqrt{t - z}} \frac{dt}{t^2}. \quad (44)$$

If we now apply the argument principle to $\Omega'_k(z)$ in the same manner as it was applied

in I to $A'_k(z)$ then we find that $\Omega'_k(z)$ can have either 3 or 5 zeros in the finite cut plane. However, in either case there is only one real zero in $(0, \alpha)$. The question as to which case it is, i.e. 3 or 5 zeros, can be established once values of k, α and β are specified. Consequently we quote only the relevant factorizations. For the case of 3 zeros we have

$$\Omega'_k(z) = \frac{(z - x_k)(z - z'_{k1})(z - \bar{z}'_{k1})}{z^3(z - \alpha)\sqrt{\beta - z}} H_k(z), \quad (45)$$

and for the case of 5 zeros,

$$\Omega'_k(z) = \frac{(z - x_k)(z - z'_{k1})(z - \bar{z}'_{k1})(z - z'_{k2})(z - \bar{z}'_{k2})}{z^3(z - \alpha)(z - \beta)^2\sqrt{\beta - z}} H_k(z) \quad (46)$$

where z'_{ki} and \bar{z}'_{ki} , $i=1, 2$, are the remaining zeros, not of interest here, and

$$H_k(z) = \frac{1}{2} \left(\frac{1}{\alpha} + \frac{1}{\beta} \right) \exp \left\{ \frac{1}{\pi} \int_{-\infty}^0 \arg \Omega_k'^+(t) \frac{dt}{t - z} + \frac{1}{\pi} \int_{\alpha}^{\beta} \arg \Omega_k'^+(t) \frac{dt}{t - z} + \frac{1}{\pi} \int_{\beta}^{\infty} \left(\arg \Omega_k'^+(t) - \frac{\pi}{2} \right) \frac{dt}{t - z} \right\}. \quad (47)$$

Once the value of x_k has been determined, we may easily find the corresponding value of M , say M_k , from Equation (44) as

$$M_k = \frac{2}{3} \left\{ \frac{1}{\alpha\sqrt{\alpha - x_k}} + \frac{1}{\beta\sqrt{\beta - x_k}} \right\}. \quad (48)$$

Consequently the condition for two real roots in this case will be, on taking inequality (13) into account,

$$\frac{2}{3} \left\{ \frac{1}{\alpha\sqrt{\alpha - x_k}} + \frac{1}{\beta\sqrt{\beta - x_k}} \right\} < M < \frac{(k+1)\pi}{\alpha\sqrt{\alpha}} - \frac{1}{\beta\sqrt{\alpha}} \left\{ \sqrt{\frac{\beta}{\alpha} - 1} + \frac{\beta}{\alpha} \tan^{-1} \sqrt{\frac{\beta}{\alpha} - 1} \right\}. \quad (49)$$

Finally we collect together our principal results for the elliptic orbits. For the case in which the shaded region A contains neither the attracting focus nor the empty focus, depicted generically by Figure 3, the relevant inequality for M from I, is

$$\frac{2}{3} (\alpha^{-3/2} - \beta^{-3/2}) < M < \frac{1}{\beta\sqrt{\alpha}} \left[\sqrt{\frac{\beta}{\alpha} - 1} + \frac{\beta}{\alpha} \tan^{-1} \sqrt{\frac{\beta}{\alpha} - 1} \right]. \quad (50)$$

For the case in which A contains S but not S^* , as shown in Figure 4, the inequality is

$$\frac{2}{3} (\alpha^{-3/2} + \beta^{-3/2}) < M < \frac{\pi}{\alpha\sqrt{\alpha}} - \frac{1}{\beta\sqrt{\alpha}} \left[\sqrt{\frac{\beta}{\alpha} - 1} + \frac{\beta}{\alpha} \tan^{-1} \sqrt{\frac{\beta}{\alpha} - 1} \right]. \quad (51)$$

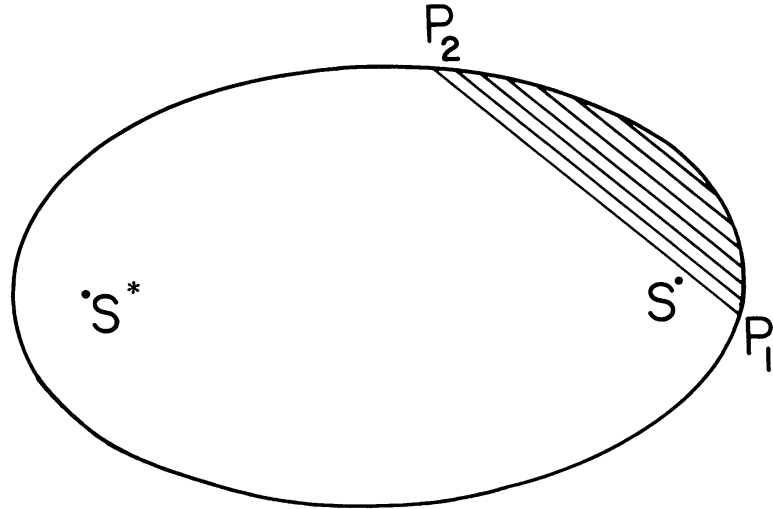


Fig. 3. Orbit basic to inequality (50).

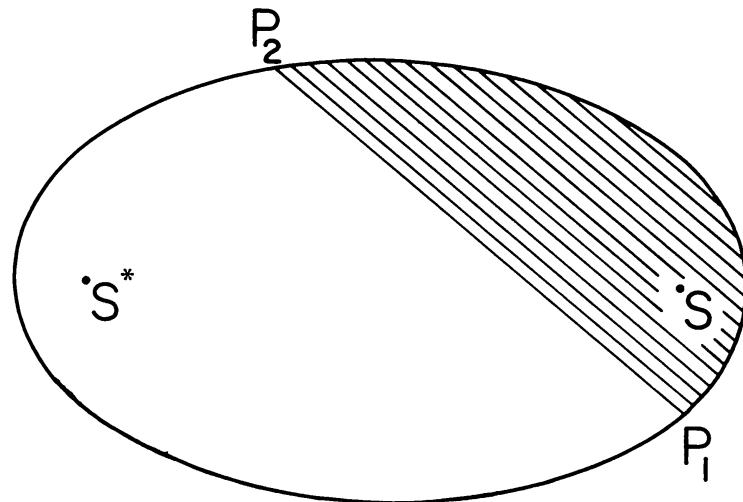


Fig. 4. Orbit basic to inequality (51).

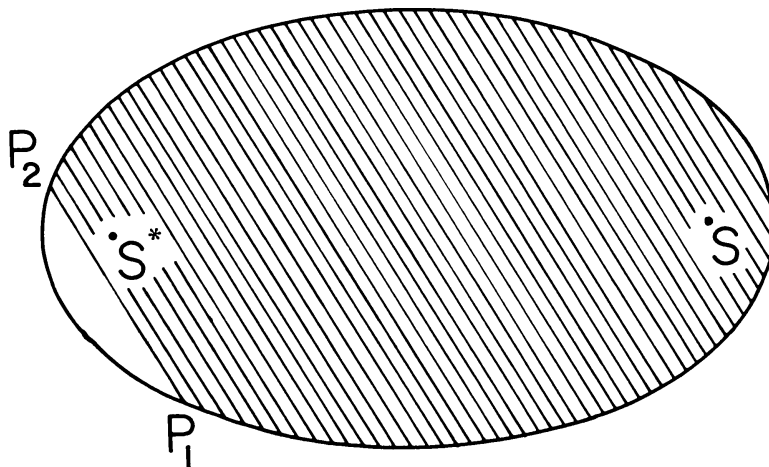


Fig. 5. Orbit basic to inequality (52).

If both S and S^* are included in A , as shown in Figure 5, the inequality for M from I is

$$\frac{\pi}{\alpha\sqrt{\alpha}} - \frac{1}{\beta\sqrt{\alpha}} \left[\sqrt{\frac{\beta}{\alpha} - 1} + \frac{\beta}{\alpha} \tan^{-1} \sqrt{\frac{\beta}{\alpha} - 1} \right] < M. \quad (52)$$

Finally, for the case in which S^* is included in A , but S is not, see Figure 6, we have

$$\frac{1}{\beta\sqrt{\alpha}} \left[\sqrt{\frac{\beta}{\alpha} - 1} + \frac{\beta}{\alpha} \tan^{-1} \sqrt{\frac{\beta}{\alpha} - 1} \right] < M. \quad (53)$$

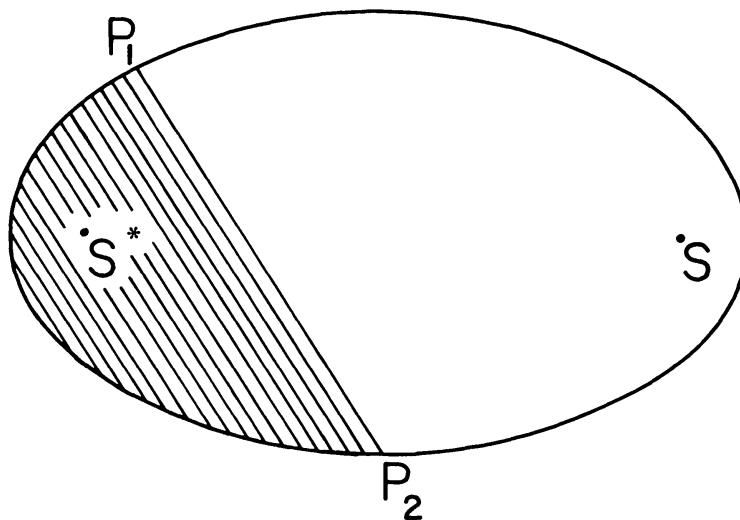


Fig. 6. Orbit basic to inequality (53).

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